Principal Algebraic Group Actions

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Example: Let $X = \mathbb{T}^{\Gamma}$ with $\mathbb{T} = \mathbb{R}/\mathbb{Z}$, and let λ be the left shift-action on X, defined by $(\lambda^{\gamma} x)_{\theta} = x_{\gamma^{-1}\theta}$ for every $x = (x_{\theta})_{\theta \in \Gamma} \in X$. The right shift-action $\gamma \mapsto \rho^{\gamma}$ of Γ on X is given by $(\rho^{\gamma} x)_{\theta} = x_{\theta\gamma}$. The

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Let $f = \sum_{\gamma \in \Gamma} f_{\gamma} \gamma \in \mathbb{Z}[\Gamma]$. Define a group homomorphism $\rho^f : X \longrightarrow X$ by $\rho^f = \sum_{\gamma \in \Gamma} f_{\gamma} \rho^{\gamma}$ (this is effectively right convolution by $f^* = \sum_{\gamma \in \Gamma} f_{\gamma} \gamma^{-1}$). Then ρ^f commutes with λ .

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Let $X_f = \ker(\rho^f)$, $\alpha_f = \lambda|_{X_f}$. This is the principal Γ -action defined by f.

For $\Gamma = \mathbb{Z}$, every $f = \sum_{n \in \mathbb{Z}} f_n n \in \mathbb{Z}[\mathbb{Z}]$ can be viewed as the Laurent polynomial $\sum_{n \in \mathbb{Z}} f_n u^n$. After multiplication by a power of u (which doesn't change X_f) we may assume that $f = \sum_{k=0}^n f_k u^k$ with nonzero f_0 and f_n . Then

$$X_f = \{x = (x_m) \in \mathbb{T}^{\mathbb{Z}} : f_0 x_m + \dots + f_n x_{m+n} = 0 \text{ for all } m \in \mathbb{Z}\}.$$

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If $f_n = |f_0| = 1$, α_f is (conjugate to) the toral automorphism given by the companion matrix

$$A_{f} = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \\ -f_{0} & -f_{1} & -f_{2} & \cdots & -f_{n-1} \end{pmatrix}$$

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Dynamical properties like ergodicity or expansiveness are determined by the roots of f, and the entropy of α_f is given by

$$h(\alpha_f) = \log |f_n| + \sum_{\{c:f(c)=0\}} \log^+ |c| = \int_0^1 \log |f(e^{2\pi is})| \, ds.$$

Other Examples Of Principal Z-actions

• f = u - 2. The automorphism α_f factors onto multiplication by 2 on $\mathbb{T} = \mathbb{R}/\mathbb{Z}$. α_f is expansive and has entropy log 2.

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- f = 2u 3. The automorphism α_f is 'multiplication by 3/2' on $\mathbb{T} = \mathbb{R}/\mathbb{Z}$ (it is the shift on the space of sequences $(x_n)_{n \in \mathbb{Z}} \in \mathbb{T}^{\mathbb{Z}}$ which satisfy $2x_{n+1} = 3x_n$ for every *n*). α_f is expansive and has entropy log 3.

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- f is cyclotomic (e.g., f = u² + u + 1). In this case α_f is of finite order and hence nonergodic with entropy 0. For f = u² + u + 1, α_f³ = Id.

For $\Gamma = \mathbb{Z}^d$ we write $f \in \mathbb{Z}[\Gamma]$ as a Laurent polynomial in d variables: $f = \sum_{\mathbf{n} \in \mathbb{Z}^d} f_{\mathbf{n}} \mathbf{n} = \sum_{\mathbf{n} \in \mathbb{Z}^d} f_{\mathbf{n}} u^{\mathbf{n}}.$

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- The entropy $h(\alpha_f)$ is given by the *logarithmic Mahler measure* of f:

$$h(\alpha_f) = \int_0^1 \cdots \int_0^1 \log |f(e^{2\pi i t_1}, \dots, e^{2\pi i t_d})| dt_1 \cdots dt_d$$

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- The action α_f is Bernoulli if and only if f is not divisible by a generalized cyclotomic polynomial (Rudolph-S, 1995).

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The pairing $\langle f, x \rangle = e^{2\pi i \sum_{\gamma \in \Gamma} f_{\gamma} x_{\gamma}}$, $f = \sum_{\gamma \in \Gamma} f_{\gamma} \gamma \in \mathbb{Z}[\Gamma]$, $x = (x_{\gamma}) \in \mathbb{T}^{\Gamma}$, identifies $\mathbb{Z}[\Gamma]$ with the dual group of \mathbb{T}^{Γ} . Under this identification.

$$X_f = (\mathbb{Z}[\Gamma]f)^{\perp}$$
 and $\widehat{X}_f = \mathbb{Z}[\Gamma]/\mathbb{Z}[\Gamma]f$,

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The principal action α_f is ergodic if and only if the orbit of every nonzero $a \in \widehat{X}_f = \mathbb{Z}[\Gamma]/\mathbb{Z}[\Gamma]f$ is infinite.

In other words, α_f is nonergodic if and only if there exist an $a = h + \mathbb{Z}[\Gamma]f \in \mathbb{Z}[\Gamma]/\mathbb{Z}[\Gamma]f$ with $h \notin \mathbb{Z}[\Gamma]f$, and a finite-index subgroup $\Delta \subset \Gamma$, such that $h - \delta h \in \mathbb{Z}[\Gamma]f$ for every $\delta \in \Delta$.

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A cocycle of the form (*) is a *coboundary* if there exists a $b \in \mathbb{Z}[\Gamma]$ such that $c(\delta) = b - \delta b$ for every $\delta \in \Delta$.

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If c in (\star) were a coboundary, then $h - \delta h = c(\delta)f = bf - \delta bf$ and hence (since f is not a right zero-divisor) $h = bf \in \mathbb{Z}[\Gamma]f$ – contrary to our assumption about h.

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Conclusion: if f is not a right zero-divisor, then α_f is nonergodic if and only if there exists a finite index subgroup $\Delta \subset \Gamma$ and a cocycle $c \colon \Delta \longrightarrow \mathbb{Z}[\Gamma]$ which is not a coboundary, but such that cf is a coboundary.

Theorem. If Γ is finitely generated and amenable, $\Delta \subset \Gamma$ a finite-index subgroup and $c \colon \Delta \longrightarrow \mathbb{Z}[\Gamma]$ a cocycle, then there exists a bounded map $v \colon \Gamma \longrightarrow \mathbb{Z}$ such that $c(\delta) = v - \lambda^{\delta} v$ for every $\delta \in \Delta$.

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Corollary. If Γ is finitely generated, amenable, and not virtually cyclic, then every cocycle $c \colon \Delta \longrightarrow \mathbb{Z}[\Gamma]$ is a coboundary.

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Virtual cyclicity has to be excluded: if $\Gamma = \mathbb{Z}$ and $v = (v_n)$ with $v_n = 1$ for $n \ge 0$ and $v_n = 0$ for n < 0, then the equation $c(m) = v - \lambda^m v$ defines a cocycle $c : \mathbb{Z} \longrightarrow \mathbb{Z}[\mathbb{Z}]$ which is not a coboundary.

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In general, nontrivial cocycles $c: \Delta \longrightarrow \mathbb{Z}[\Gamma]$ exist if and only if the group Γ has more than one end: for every k, the 'level set' $L_k = \{\gamma \in \Gamma : v_{\gamma} = k\}$ of v must be almost left invariant under Δ , since $v - \lambda^{\delta} v \in \mathbb{Z}[\Gamma]$. If all but one of these level sets are finite, then $v - k \in \mathbb{Z}[\Gamma]$ for some k and c is a coboundary. If two of these level sets are infinite, Δ (and hence Γ) has more than one end (by definition).

Theorem. Let Γ be a countably infinite discrete group and $f \in \mathbb{Z}[\Gamma]$ an element which is not a right zero-divisor. Then α_f is ergodic if one of the following conditions hold.

- Γ is amenable and contains a finitely generated, infinite, and not virtually cyclic subgroup.
- Γ is infinitely generated (Hayes).
- Γ has property T (Li).
- Γ is the free group on $k \ge 2$ generators (Hayes).

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The last of these statements is the most interesting one. If Γ is free, then every finite-index subgroup $\Delta \subset \Gamma$ is again free with more than one generator. Free groups have infinitely many ends, so that there exist many cocycles which are not coboundaries. *However, these nontrivial cocycles have the property that cf is not a coboundary*.

The Zero Divisor Conjecture is known to hold if Γ is virtually abelian, elementary amenable, or orderable. (Γ is *elementary amenable* if it lies in the smallest class of groups which contains the finite and the abelian groups, and which is closed under taking subgroups, quotients, extensions, and directed unions).

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If Γ has an element of finite order $x^n = 1$, then $\mathbb{Z}\Gamma$ has zero-divisors: $(x-1)(1 + x + \cdots + x^{n-1}) = 0$.

If uv = 0, but u and v are nonzero, one calls u a left zero-divisor and v a right zero-divisor.

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Interesting fact: If Γ is amenable and $u \in \mathbb{Z}\Gamma$ is a left zero-divisor, then it is also a right zero-divisor. The proof uses von Neumann algebra techniques.

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This shows that there can be very complicated divisors of zero!

Entropy Of Principal Actions Of Amenable Groups

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Theorem: If Γ is amenable and f is not a zero-divisor, then

 $h(\alpha_f) = \log \det_{\mathcal{N}\Gamma}(\rho_f), \tag{1}$

where the last term is the *Fuglede-Kadison determinant* of f, acting by right convolution on $\ell^2(\Gamma)$, and viewed as an element of the (left-equivariant) group von Neumann algebra $\mathcal{N}\Gamma$.

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The proof of (1) is due to Deninger (2006, assuming expansiveness + technical conditions), Deninger-S (2007, assuming expansiveness + residual finiteness of Γ) and Li-Thom (2012, general case).

Theorem (Deninger-S, 2007): If Γ is amenable and α_f is expansive, then

$$h(\alpha_f) = \lim_{\Delta \searrow \{1\}} \frac{1}{|\Gamma/\Delta|} \log |\operatorname{Fix}_{\Delta}(X_f)| = \log \operatorname{det}_{\mathcal{N}\Gamma}(\rho_f).$$
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For every finite-index subgroup $\Delta \subset \Gamma$, $|Fix_{\Delta}(X_f)| = |\det \rho_f^{\Gamma/\Delta}|$. The convergence in (2) as $\Delta \searrow \{1\}$ follows from an approximation argument due to Lück (1994) and Schick (2001).

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If α_f is nonexpansive, equality of the three terms in (2) is an open problem — even for $\Gamma = \mathbb{Z}^d$!