

①

arXiv: 1409.6496
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$$z = Tx + \delta j$$

- $x \in X$ unknown
- z obs
- $T: X \rightarrow Y$ bdd op (blurring)
- $j \sim N(0, I)$ noise, $\delta > 0$ known noise level.

Prior: $x \sim N(m_0, \frac{\delta^2}{\alpha} C_0)$, $\alpha > 0$ scaling parameter
 \downarrow
 $\alpha > 0, \epsilon - c$
 α assume C_0, T commuting (exact meaning in a moment)

Likelihood: $z|x \sim N(Tx, \delta^2 I)$ (linear model density of prior & likelihood quadratic in x)

\Rightarrow Posterior: $x|z \sim N(x_2^\delta, C(\alpha, \delta)) = \mu_{\alpha, \delta}^z$

- 1) Introduce Setup
- 2) Posterior Construction
- 3) Delayed solution by precoding the prior
- (4) General technique for getting ROC

(2)

Complete the square

$$C^{-1} = \frac{\alpha}{\delta^2} C_0^{-1} + \frac{1}{\delta^2} T^* T = \delta^{-2} C_0^{-1/2} (\alpha I + B^* B) C_0^{-1/2}$$

$$B = T C_0^{1/2}$$

compact

$$C^{-1} (x_{\alpha}^{\delta} - m_0) = \delta^{-2} T^* (z - T m_0)$$

$$\Leftrightarrow x_{\alpha}^{\delta} = C_0^{1/2} (\alpha I + B^* B)^{-1} B^* (z - T m_0) + m_0$$

ignore $T m_0$, x_{α}^{δ} is regularized inversion of data,

α acts as reg. parameter

(if $\alpha=0$ " $x_0^{\delta} = C_0^{1/2} (B^* B)^{-1} B^* z = T^{-1} z$)

Posterior Consistency: Assume $z = z^{\delta} = T x^* + \delta \epsilon$

small noise limit

x^* fixed truth

As $\delta \rightarrow 0$, can we choose $\alpha = \alpha(\delta) \rightarrow 0$

s.t. " $\mu_{\alpha, \delta}^{z=z^{\delta}} \rightarrow \delta_{x^*}$ " ?

reg needs to disappear

③

For us " \rightarrow " is in the sense of SPC

$$SPC = \mathbb{E}^{X^y} \mathbb{E}_\alpha^{\tilde{z}^y} \|X^y - X\|^2$$

\uparrow wrt data generating measure $\mathcal{N}(TX^y, \delta I)$
 \uparrow wrt posterior $p_{\alpha, \delta}^{\tilde{z}^y}$

$$= \mathbb{E}^{X^y} \left(\|X^y - X_\alpha^\delta\|^2 + \text{tr}(C(\alpha, \delta)) \right)$$

bias-variance decomposition of ~~over~~ expectation wrt post 1-step \rightarrow data

$$= \|X^y - \mathbb{E}^{X^y} X_\alpha^\delta\|^2 + \mathbb{E}^{X^y} \|X_\alpha^\delta - \mathbb{E}^{X^y} X_\alpha^\delta\|^2 + \text{tr}(C(\alpha, \delta))$$

bias-variance \rightarrow \downarrow squared bias \downarrow estimation variance \downarrow posterior spread
 \downarrow \rightarrow expectation wrt data
of post mean as estimate of X^y

Assume $X^y \in X^\gamma$, γ quantity regularly assumed to be known (unrealistic)

As $\delta \rightarrow 0$, choose $\alpha = \alpha(\delta, \gamma) \rightarrow 0$ s.t. $SPC \rightarrow 0$

at optimal rate (minimum over ~~all~~ X^y).

(4)

eg KVZ11, ALS13,
moderately bad problem

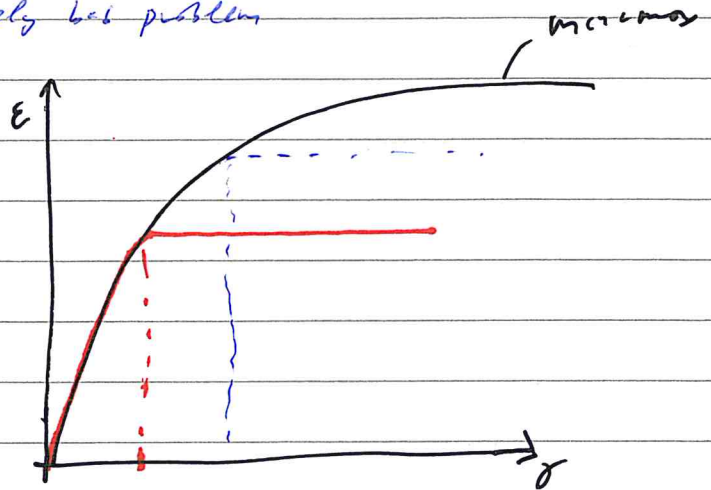
KVZ12, ASZ14
severely bad problem

Typical picture

SPC $\sim \sigma^2 \epsilon$

Saturation phenomenon

due to saturation of bias



(since only term which depends $\sim x^*$)

Contributions: a) Use classic reg. tools to get
SPC rates in general settings
(before relied on explicit calc.)

b) Show that choosing prior mean
as regularized inverse of data
delays or even removes saturation
in bias (hence SPC)

will try
to explain

this - if I have

time I will give simplified version of a).

↓
bias or bias

(5)

$\neq m_0 = 0$ bias $b_{x^*}(\alpha) = \|x^* - \mathbb{E}^{x^*} x_{\alpha}^{\delta}\|$

$$= \|x^* - C_0^{1/2} (\alpha I + B^* B)^{-1} B^* T x^*\|$$

$$= \| (I - (\alpha I + B^* B)^{-1} B^* B) x^* \|$$

$$= \alpha \| (\alpha I + B^* B)^{-1} x^* \|$$

at best $O(1)$ as $\alpha \rightarrow 0$

This happens if $x^* \in R(B^* B)$

so that $(B^* B)^{-1} x^* \in X$

If not, norm blow up as $\alpha \rightarrow 0$, like slower than $1/\alpha$
(provided $x^* \in X$) (so that $\alpha \cdot \| \cdot \| \rightarrow 0$)

Choose $m_0 = m_{\alpha}^{\delta} = C_0^{1/2} g_{\alpha}(B^* B) B^* z^{\delta}$

reg. filter ~~filter~~

- $g_{\alpha}(B^* B)$ bdd $\forall \alpha > 0$

$$\cdot g_{\alpha}(B^* B) \xrightarrow{\alpha \rightarrow 0} (B^* B)^{-1}$$

• associated residual $r_{\alpha}(t) = 1 - \delta g_{\alpha}$
 $r_{\alpha} \xrightarrow{\alpha \rightarrow 0} 0$

eg Tikhonov: $g_{\alpha}(t) = \frac{1}{\alpha + t}$

$$r_{\alpha}(t) = \frac{\alpha}{\alpha + t}$$

Spectral cut-off: $g_{\alpha}(t) = \begin{cases} \frac{1}{t} & t \geq \alpha \\ 0 & t < \alpha \end{cases}$

$$r_{\alpha}(t) = \begin{cases} 0 & t \geq \alpha \\ 1 & t < \alpha \end{cases}$$

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eg Tikhonov: $g_\alpha(t) = \frac{1}{\alpha + t}$, $v_\alpha(t) = \frac{\alpha}{\alpha + t}$ (veg induced by known prior for $v_0=0$)

Spectral cut-off: $g_\alpha(t) = \begin{cases} 1/t & , t \geq \alpha \\ 0 & , t < \alpha \end{cases}$

$$v_\alpha(t) = \begin{cases} 0 & , t \geq \alpha \\ 1 & , t < \alpha \end{cases}$$

Then $b_{x^*}(\alpha) = \dots = \alpha \| (\alpha + B^*B)^{-1} v_\alpha (B^*B) x^* \|$

eg Tikhonov $= \alpha^2 \| (\alpha + B^*B)^{-2} x^* \|$

can at best be $O(1)$

for $x^* \in R((B^*B)^2)$

if not, norm blows up slower than $1/\alpha^2$

Delayed saturation! (full picture)

(7)

Now try to explain a)

• φ index function if cts nondecreasing, $\varphi(0) = 0$.

• Qualification: φ qualification for reg g_α if

$$V_\alpha(t)\varphi(t) \leq C\varphi(\alpha) \quad \forall \alpha, t.$$

Quantifies ability of reg to take smoothness into account.

eg Tikhonov $V_\alpha(t) = \frac{\alpha}{\alpha+t} t \leq \alpha$ (this is what we have for $m_0=0$)

so that $\varphi(t) = t$ (maximal) qualification.

• If φ qualification for g_α , then any $\psi \prec \varphi$ also qualification for g_α .
↓ goes to a slower rate

eg $\frac{\alpha}{\alpha+t} t^k \leq \alpha^k$ since $\alpha^k t^k \leq \alpha+t$.

~~eg~~
eg spectral cut off $V_\alpha(t) = \begin{cases} 0 & t \geq \alpha \\ \varphi & t < \alpha \end{cases}$

$$V_\alpha(t)\varphi(t) = 0 \leq \varphi(\alpha) \quad t \geq \alpha$$

$$V_\alpha(t)\varphi(t) = \varphi(t) \leq \varphi(\alpha), \quad t \leq \alpha \quad (\varphi \text{ non-decreasing})$$

TSVD has arbitrary qualification.

⑧

Assume $x^* \in A_\varphi = \{x: x = \varphi(B^*B)w, \|w\| \leq 1\}$

Proposition:

i) If $\varphi(t) \prec t$, $b_{x^*}(\alpha) \leq c \varphi(\alpha)$
(low smoothness)
independently of m_0 .

ii) If $t \prec \varphi(t)$ and $m_0 = 0$, $b_{x^*}(\alpha) \asymp \alpha$
(high smoothness)

iii) If $t \prec \varphi(t)$ and $\frac{\varphi(t)}{t}$ quadratically for φ_α
 $b_{x^*}(\alpha) \leq c \varphi(\alpha)$.

Proof:

i) $\| \alpha (\alpha I + B^*B)^{-1} \varphi(B^*B)w \| \leq \| \alpha (\alpha I + B^*B)^{-1} \varphi(B^*B) \|$
 $\leq \varphi(\alpha)$
Tikhonov quadratically φ t , $\varphi \prec t$

ii) discussed earlier

iii) $\| \alpha (\alpha I + B^*B)^{-1} v_\alpha(B^*B) \varphi(B^*B) \|$
 $= \| \alpha (\alpha I + B^*B)^{-1} (B^*B) (B^*B)^{-1} v_\alpha(B^*B) \varphi(B^*B) \|$
 $\leq \| \alpha (\alpha I + B^*B)^{-1} (B^*B) \| \| v_\alpha(B^*B) \varphi(B^*B) (B^*B)^{-1} \|$
 $\stackrel{\downarrow \text{Tikhonov}}{\leq} \alpha \frac{\varphi(\alpha)}{\alpha} = \varphi(\alpha)$

eg g_α Tikhonov. Then for $\varphi(t) = t^2$, $\frac{\varphi(t)}{t} = t$ quadratically for φ_α
 $\Rightarrow b_{x^*}(\alpha) \leq \alpha^2$ (delayed saturation)

eg g_α Spectral cut-off. never saturates

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To allow for more flexibility define

$$A_\varphi = \{x; x = \varphi(C_0)w, \|w\| \leq 1\}$$

or introduce link condition between T and C_0 .