# Bayesian Methods in Neuroimaging 

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## SAMSI Program



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## Home , Programs

## 2015-16: Challenges in Computational Neuroscience (CCNS)

Recently the NIH Brain Research through Advancing Innovative Neurotechnologies Initiative (BRAIN) was announced, which is part of a new Presidential focus aimed at revolutionizing studies of the human brain. Neuroscience is accumulating exponentially growing volumes of data and knowledge on specific aspects of the healthy and diseased brain, in different species, at different ages as BRAIN and Human brain projects gather momentum. Brain theory, modeling, and statistics will be essential to turn knowledge into better understanding of the brain, even though this is a formidable task.

To meet this critical need and important challenge, we must develop sophisticated mathematical and statistical methods in neuroscience to understand the underying mechanisms that bridge multiple spatial and temporal scales, linking the activity of individual components (e.g., atoms, genes, or neurons), and their interactions to the dynamic behavior of the complex brain system. These important issues have attracted the attention of researchers in engineering, computer science, applied mathematics, as well as statistics.

The Challenges in Computational Neuroscience (CCNS) program builds upon three earlier fullyear programs on Analysis of Object Oriented Data (AOOD) (2010-2011), Massive Dataset (MD) (2012-2013), and Low-dimensional Structure in High-dimensional Systems (LDHD) (2013-2014). The previous general programs have offered a good starting point, a solid foundation, which enables the participants of the CCN program to further address unique challenges imposed by the problems in computational neuroscience.

The CCNS program will focus on the following research topics:

- Inverse problems
- Signal processing
- Machine learning


## Academic Year of Program

When: August 1, 2015 - May 30, 2016

## Organizing Committee

Program Leaders:
Hongtu Zhu
Local Scientific Coordinators:
David Dunson
J. S. Marron

Ezra Miller
Haipeng Shen
Rul Song

## Outline

(1) Introduction
(2) Neuroimaging Examples
(3) Alternatives to MCMC
(4) Parallelization
(5) Concluding Remarks

## Bayes Theorem

$$
\pi(\theta \mid Y)=\frac{\pi(Y \mid \theta) \pi(\theta)}{\pi(Y)}
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- $\pi(\theta \mid y)$ - posterior density


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Simple, yet profound

## Example-Gaussian Data

- $Y=\left(Y_{1}, \ldots, Y_{n}\right)$, where each $Y_{i}$ is Gaussian dist:

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\left[Y_{i} \mid \mu\right] \sim \mathrm{N}\left(\mu, \sigma^{2}\right)
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- $\mu \sim \mathrm{N}\left(\nu, \phi^{2}\right)$
- $\nu, \phi^{2}$ and $\sigma^{2}$ known constants
- Then

$$
[\mu \mid Y] \sim \mathrm{N}(m, v)
$$

where

$$
\begin{aligned}
v & =\frac{\sigma^{2} \phi^{2}}{n \phi^{2}+\sigma^{2}} \\
m & =\left(\frac{\sum_{i}^{n} y_{i}}{\sigma^{2}}+\frac{\nu}{\phi^{2}}\right) / v
\end{aligned}
$$

## Example (cont.)

- This example is a simple "toy example" with a simple posterior distribution


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Must rely on Monte Carlo simulation techniques

## Monte Carlo Simulation

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...to name a few
- Theory guarantees these all converge to the posterior distribution
- No guarantee how long it will take


## Monte Carlo Simulation

- For complex problems, including those in Neuroimaging,
- these (MC)MC simulations methods computationally intense - "behave poorly"-samples highly correlated (called slow mixing)


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- For complex problems, including those in Neuroimaging,
- these (MC)MC simulations methods computationally intense
- "behave poorly"-samples highly correlated (called slow mixing)
- Must run the simulation a very long time to obtain good estimates of the posterior
- Weeks to months

Back to this latter

## Pre-surgical fMRI

Liu, Z., Berrocal, V. J., Bartsch, A. J., Johnson, T. D. (2014) Pre-Surgical fMRI data analysis using a spatially adaptive conditionally autoregressive model. Submitted to Bayesian Analysis.

- Standard fMRI methods have too strict control of false positives


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- Don't want to cut out functionally eloquent regions by mistake


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- Standard fMRI methods have too strict control of false positives
- For pre-surgical fMRI, control of false negatives is vital
- Don't want to cut out functionally eloquent regions by mistake
- As is control of smoothing between boundaries of high and low signal intensity
- Want to smooth where signal changes slowly
- Don't want to smooth where signal is rapidly changing

This motivates our approach

## Pre-surgical fMRI—Our Approach

- At voxel $i$ model the signal indep. with mean $\mu_{i}$ and var. $\sigma_{i}^{2}$
- Place a spatially adaptive CAR model on the $\mu_{i}$
- Spatially correlates the means
- Spatially adapts smoothness to the image

$$
\begin{aligned}
{\left[Y_{i} \mid \mu_{i}, \sigma_{i}^{2}\right] } & \sim \mathrm{N}\left(\mu_{i}, \sigma_{i}^{2}\right) \\
{\left[\mu_{i} \mid \mu_{-i}, \sigma_{i}^{2}\right] } & \sim \mathrm{N}\left(\sum_{j \sim i} \mu_{j} / N_{i}, c_{i} \sigma_{i}^{2}\right) \\
{\left[\ln \left(\sigma_{i}^{2}\right) \mid \ln \left(\sigma_{-i}^{2}\right), \phi^{2}\right] } & \sim \mathrm{N}\left(\sum_{j \sim i} \ln \left(\sigma_{j}^{2}\right) / N_{i}, \phi^{2} / N_{i}\right) \\
c_{i}=p_{i} /\left(1-p_{i}\right), & p_{i} \sim \operatorname{Beta}(\alpha, \beta)
\end{aligned}
$$

$p_{i}$ controls the amount of smoothing in the full conditional of $\mu_{i}$

## Pre-surgical fMRI—Our Approach

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- With the guidance of a subject area expert
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We compare results with those from two other spatially adaptive CAR models

Speed: Fast, about 1 hour

## Pre-surgical fMRI—Results



## Group Level fMRI Analysis

Xu, L., Johnson, T. D., Nichols, T. E., Nee, D. (2009) Modeling inter-subject variability in fMRI activation location: a Bayesian hierarchical spatial model. Biometrics 65 1041-1051.

## Study of Proactive Interference Resolution

- Proactive interference occurs when current information is lost because it is mixed up with previously learned, similar, information


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## Study of Proactive Interference Resolution

- Proactive interference occurs when current information is lost because it is mixed up with previously learned, similar, information
- One's ability to resolve proactive interference is key to in determining how much information one can store in short term memory


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- Performance decrease a marker of proactive interference
- The left lateral prefrontal cortex is a region linked to proactive interference resolution


## Group Level fMRI Analysis-Overview of Our Approach

A Bayesian Spatial Hierarchical Model

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- Level 4: Dirichlet process prior
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SLOW—days to converge

## Group Level fMRI Analysis—Patient Level Results (Sbj 4)



## Group Level fMRI Analysis—Patient Level Results (Sbj 6)



## Group Level fMRI Analysis—Patient Level Results (Sbj 13)



## Group Level fMRI Analysis—Patient Level Results (Sbj 15)



## Group Level fMRI Analysis-Marginal PPD of Ind Centers



## Group Level fMRI Analysis—Marginal PPD of Population Centers



## Other Areas

For every imaging problem there is a Bayesian solution

- Review paper:
- Zhang, L., Guindani, M., Vannucci M. (2014) Bayesian Models for fMRI Data Analysis, WIRES: Computational Statistics (to appear)
- Particle Filtering:
- Aston, J. A. D., Johansen, A. D. (2014) Bayesian Inference on the Brain: Bayesian Solutions to Selected Problems in Neuroimaging, To appear in Proceedings of the IWBCTA 2013, Varanasi, India..


## Algorithms

## Approximation Algorithms

## Stochastic

- Hamiltonian Monte Carlo (HMC)
- Reimannian Manifold HMC (RMHMC)

Deterministic

- Variational Bayes (VB)
- Integrated Nested Laplacian Approximation (INLA)


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Partial derivatives of the Hamiltonian determine how $q$ and $p$ change over time

## HMC

Hamiltonian (partial differential) equations:

$$
\begin{aligned}
& \frac{d q_{i}}{d t}=\frac{\partial H(q, p)}{\partial p_{i}}=\frac{\partial K(p)}{\partial p_{i}} \\
& \frac{d p_{i}}{d t}=-\frac{\partial H(q, p)}{\partial q_{i}}=-\frac{\partial U(q)}{\partial q_{i}}
\end{aligned}
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\end{aligned}
$$

For HMC:

- $U(q)$-minus the log posterior density
- $K(p)=\frac{1}{2} p^{\prime} M^{-1} p$
- $M$ is a SPD matrix, typically a scalar multiple of the identity matrix
- IF analytic solution to Hamilton equations, we have a deterministic solution to our Bayesian problem
- Typically need to solve equations numerically


## HMC

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\end{aligned}
$$

For HMC:

- Integrals approx. by iterating with the Leapfrog Method
- Solution will be biased (due to approx. error) unless
- Metropolis update performed (either accept or reject current state)
- Acceptance rates typically high (so almost deterministic solution)
- Mixing typically much faster than Metropolis-Hastings
- Don't have to draw as many samples
- http://mc-stan.org


## RMHMC

## For RMHMC:

- $K(q, p)=\frac{1}{2} p^{\prime} M^{-1}(q) p$
- Don't need to guess $M(q)$
- Automatically adjusts to geometry of parameter manifold
- $M(q)$ is expected Fisher info. matrix + negative Hessian of log-prior
- For RMHMC, need the inverse of $M(q)$ (no longer diagonal)
- In most imaging problems the $\operatorname{dim}$. of $\mathrm{M}(\mathrm{q})$ is too large to invert


## VB

- Approximates solution to $\pi(\theta \mid y)$ with a density $q(\theta)$
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- Restrict $q$ to a manageable class of densities
- $q(\theta)=\prod_{i=1}^{p} q_{i}\left(\theta_{i}\right)$ (mean-field approximation)
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- Minimize the K-L distance between $q(\theta)$ and $\pi(\theta \mid y)$ :

$$
\int q(\theta) \ln \left[\frac{q(\theta)}{\pi(\theta \mid y)}\right] d \theta
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- Iterate until some convergence criteria is met
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- Iterate until some convergence criteria is met
- KEY: find a good variational density $q$ that is much easier to deal with than $\pi(\theta \mid y)$
- Typically much faster than MCMC
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- Iterate until some convergence criteria is met
- KEY: find a good variational density $q$ that is much easier to deal with than $\pi(\theta \mid y)$
- Typically much faster than MCMC
- However, posterior variances underestimated-sometimes severely


## INLA

Consider the posterior of a latent Gaussian model: $\pi(x, \theta \mid y)$ Posterior marginals are

$$
\begin{aligned}
\pi\left(x_{i} \mid y\right) & =\int \pi\left(x_{i} \mid \theta, y\right) \pi(\theta \mid y) d \theta \\
\pi\left(\theta_{j} \mid y\right) & =\int \pi(\theta \mid y) d \theta_{-j}
\end{aligned}
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& \pi\left(\theta_{j} \mid y\right)=\int \pi(\theta \mid y) d \theta_{-j}
\end{aligned}
$$

Construct nested approximations:

$$
\begin{aligned}
\tilde{\pi}\left(x_{i} \mid y\right) & =\int \tilde{\pi}\left(x_{i} \mid \theta, y\right) \tilde{\pi}(\theta \mid y) d \theta \\
\tilde{\pi}\left(\theta_{j} \mid y\right) & =\int \tilde{\pi}(\theta \mid y) d \theta_{-j}
\end{aligned}
$$

## INLA

Now

$$
\left.\pi(\theta \mid y) \approx \tilde{\pi}(\theta \mid y) \propto \frac{\pi(x, \theta, y)}{\tilde{\pi}_{G}(x \mid \theta, y)}\right|_{x=x^{*}(\theta)}
$$

This is a Laplace approx.

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approximated by another Laplacian approximation.

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- Numerical integration used to approximation the full marginals
- Very fast and accurate
- R package available that solves many problems
- http://www.r-inla.org


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- HMC:
- Need analytic derivatives
- Need to tune numerical integration step
- Theory ensures approximation error can be made arbitrarily small


## Simulation Study: HMC, VB or INLA?

- Interested in LGCPs on the brain (3D problem)


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- Assessed stat. properties of estimators from INLA, VB and HMC


## Simulation Study—Results

True Simulation Values: $\mu=5 \quad \sigma^{-2}=0.286 \quad E(N)=792.1$

| Parm | HMC |  | INLA |  | VB |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Bias | MSE | Bias(rel) | MSE(rel) | Bias(rel) | MSE(rel) |
| $\mu$ | 0.071 | 0.014 | 0.261(3.69) | 0.077(5.39) | 1.23(17.07) | 1.52(106.73) |
| $\sigma^{-2}$ | 0.015 | $6 e^{-4}$ | 0.061(4.15) | 0.004(7.01) | 0.281(19.20) | 0.079(131) |
| $E(N)$ | 0.877 | 791 | -179(-204) | 32666(41.28) | -11.36(-13) | 958.5(1.21) |

$E(N)$ is the expected number of points over the region.
It is the integrated intensity function.

## Simulation Study—Results

Relative MSE for latent GP (VB)


## Simulation Study-Results

Relative MSE for latent GP (INLA)


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- Best for task parallelization
- GPUs
- Best for data parallelization
- Extremely good at "embarrassingly parallel" operations


## GPU Example

Ge, T., Müller-Lenke, N., Bendfeldt, K., Nichols, T. E., Johnson, T. D. (2014) Analysis of Multiple Sclerosis lesions via spatially varying coefficients. AOAS 8 1095-1118.

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- Want to correlate clinical symptoms with lesion location
- Lesions segmented by Neuroradiologists
- Work with binary images as outcomes
- Spatial generalized linear model (probit or logit link)
- Clinical symptoms + nuisance covariates
- Parameters are spatially varying over the brain and are spatially correlated
- GMRF used to model the spatial correlation


## GPU Example-MS high-resolution imaging

## Data are $T_{2}$ hyperintense lesions



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## GPU Example

Covariates:

- 15 subject specific covariates
- 7 FSS, PASAT score, age, gender, disease duration
- 4 MS subtypes (dummy coded into 4 variables)


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- 15 subject specific covariates
- 7 FSS, PASAT score, age, gender, disease duration
- 4 MS subtypes (dummy coded into 4 variables)

Problem Size:

- $\approx 66$ million observations ( 275 K voxels $\times 239$ subjects)
- $\approx 41$ million spatially varying coefficients ( 275 K voxels $\times 15$ covariates)


## Spatially Varying Coefficients: Cerebellar Func. System Score



6 mm left of midline

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## GPU Example

Timing:

- 10K iterations after 20K of burning
- CPU: (Serial code). 38.67 sec/iteration ( 3.3 GHz processor, Linux)
- GPU: (Parallel code). $0.21 \mathrm{sec} / \mathrm{iteration} \mathrm{(NVIDIA} \mathrm{K20c}$, threads)
- Speed up: approximately 184 times faster.
- 13.4 days (CPU) vs. 1 hr 45 min (GPU)


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The future of Bayesian Analysis in Neuroimaging appears Bright

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