Discrete-To-Continuum Limits in Graph-Based Semi-Supervised Learning

Algorithms & Computationally Intensive Inference Seminar University of Warwick

Matthew Thorpe

Joint Work with Andrea Bertozzi (UCLA), Jeff Calder (Minnesota), Brendan Cook (Minnesota), Matt Dunlop (Courant Institute), Tan Nguyen (National University of Singapore), Stanley Osher (UCLA), Dejan Slepčev (CMU), Thomas Strohmer (UC Davis), Andrew Stuart (Caltech), Bao Wang (Utah), Adrien Weihs (Manchester) and Hedi Xia (UCLA)

Department of Statistics University of Warwick

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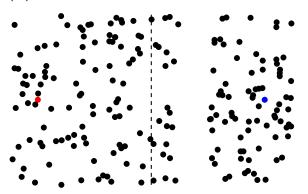
• **Problem:** Given data $\Omega_n = \{x_i\}_{i=1}^n \subset \mathbb{R}^d$ and a subset of labels $\{\ell_i\}_{i \in \mathcal{I}_n} \subset \mathbb{R}$, where $\mathcal{I}_n \subseteq \{1, \dots, n\}$, find the 'best' $u_n : \Omega_n \to \mathbb{R}$ such that $u_n(x_i) = \ell_i$ for all $i \in \mathcal{I}_n$.

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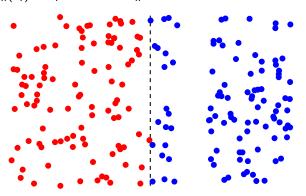
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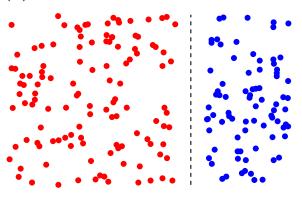
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- Assumption: Similar feature vectors should have similar labels.

Laplace Learning

1 Laplacian Regularisation: Zhu, Ghahramani and Lafferty (2003) or Zhou and Schölkopf (2005) define u_n^* as the minimiser of

$$\mathcal{E}_{n}^{(p)}(u_{n}) = \sum_{i,j=1}^{n} w_{ij} |u_{n}(x_{i}) - u_{n}(x_{j})|^{p}$$

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$$\ell_{u_n^*}(x_i) = \underset{j \in \{1, \dots, k\}}{\operatorname{argmax}} \ u_{n,j}^*(x_i).$$

3 If p = 2 it follows that u_n^* satisfies the following Laplace equation

$$L_n u_n^*(x_i) = 0$$
 if $i \notin \mathcal{I}_n$
 $u_n^*(x_i) = \ell_i$ if $i \in \mathcal{I}_n$

where $L_n u(x_i) = \sum_{j=1}^n w_{ij} (u(x_i) - u(x_j))$ is the graph Laplacian.

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- 2 p-Laplace Learning
- Poisson Learning
- Fractional Laplace Learning
- **5** Graph Neural Networks

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- **3** Let $\tilde{u}_n(x) = u_n(T_n(x))$ for some function $T_n : \Omega \to \Omega_n$.
- We will choose T_n to be an optimal transport map.

The TL^p Metric

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- Theoretically it is convenient to write:

$$\begin{split} d_{\mathrm{TL}^p}((u,\mu),(v,\nu)) &= d_{\mathrm{W}^p}(\tilde{\mu},\tilde{\nu}) = \inf_{\tilde{\pi} \in \Pi(\tilde{\mu},\tilde{\nu})} \sqrt[p]{\int_{(\Omega \times \mathbb{R}) \times (\Omega \times \mathbb{R})} |x-y|^p \, \mathrm{d}\tilde{\pi}(x,y)}. \\ \text{where } \tilde{\mu} &= \big(\mathrm{Id} \times u\big)_{\#} \mu \text{ and } \tilde{\nu} = \big(\mathrm{Id} \times v\big)_{\#} \nu. \end{split}$$

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• Numerically it is convenient to write:

$$d_{\mathrm{TL}^p}((u,\mu),(v,\nu)) = \inf_{\pi \in \Pi(\mu,\nu)} \sqrt[p]{\int_{\Omega \times \Omega} c(x,y;u,v) \, \mathrm{d}\pi(x,y)}.$$
 where $c(x,y;u,v) = |x-y|^p + |u(x)-v(y)|^p$.

Aside: A TL^p Approach to Histogram Specification



Figure: More details and other applications in T., Park, Kolouri, Rohde and Slepčev (2017).

TL^p In Practice

Theorem (García Trillos and Slepčev (2016))

If μ is absolutely continuous, then $(u_n, \mu_n) \to (u, \mu)$ in TL^p if and only if $\mu_n \rightharpoonup^* \mu$ and there exists a sequence of maps $T_n : \Omega \to \Omega$ such that $(T_n)_\# \mu = \mu_n$, $T_n \to \mathrm{Id}$ in $\mathrm{L}^p(\mu)$ and

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Assume $x_i \stackrel{\text{iid}}{\sim} \mu$ and $\mu_n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$. With probability one, there exists $T_n : \Omega \to \Omega_n$ such that $(T_n)_\# \mu = \mu_n$ and

$$\|T_n - \operatorname{Id}\|_{L^{\infty}} \lesssim \begin{cases} \frac{(\log n)^{\frac{3}{4}}}{\sqrt{n}} & \text{if } d = 2\\ \left(\frac{\log n}{n}\right)^{\frac{1}{d}} & \text{if } d \geq 3. \end{cases}$$

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Remark: by (for example) Penrose (2003) the connectivity radius of the geometric random graph scales as $\left(\frac{\log n}{n}\right)^{\frac{1}{d}}$ for all $d \in \mathbb{N}$.

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Aim: minimise

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- Formal Definition: The Laplacian regression problem is asymptotically ill-posed if constrained minimisers of $\mathcal{E}_n^{(p)}$ converge to constants.

$$\frac{1}{n^2 \varepsilon^p} \mathcal{E}_n^{(p)}(u) = \frac{1}{n^2 \varepsilon^{p+d}} \sum_{i,j=1}^n \eta\left(\frac{|x_i - x_j|}{\varepsilon}\right) |u(x_i) - u(x_j)|^p$$

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$$\approx \frac{1}{\varepsilon^{p+d}} \int \int \eta \left(\frac{|x - y|}{\varepsilon} \right) |u(x) - u(y)|^p \rho(x) \rho(y) \, \mathrm{d}x \, \mathrm{d}y$$

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= \frac{1}{\varepsilon^p} \int \int \eta(|z|) |u(y + \varepsilon z) - u(y)|^p \rho(y + \varepsilon z) \rho(y) \, \mathrm{d}y \, \mathrm{d}z$$

$$\frac{1}{n^{2}\varepsilon^{p}}\mathcal{E}_{n}^{(p)}(u) = \frac{1}{n^{2}\varepsilon^{p+d}} \sum_{i,j=1}^{n} \eta\left(\frac{|x_{i}-x_{j}|}{\varepsilon}\right) |u(x_{i}) - u(x_{j})|^{p}$$

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$$= \sigma_{\eta} \int |\nabla u(y)|^{p} \rho^{2}(y) \, \mathrm{d}y =: \mathcal{E}_{\infty}^{(p)}(u)$$

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No! Why not?

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$$\frac{1}{n^2 \epsilon_n^p} \mathcal{E}_n^{(p)}(u_n) = \frac{2}{\epsilon_n^{p+d} n^2} \sum_{j=2}^n \eta\left(\frac{|x_1 - x_j|}{\epsilon_n}\right)$$

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$$\begin{array}{l} \bullet \ \ \frac{1}{n^2 \epsilon_n^p} \mathcal{E}_n^{(p)}(u_n) = \frac{2}{\epsilon_n^{p+d} n^2} \sum_{j=2}^n \eta \left(\frac{|x_1 - x_j|}{\epsilon_n} \right) \\ = \left(\frac{2}{\epsilon_n^p n} \right) \times \left(\frac{1}{n \epsilon_n^d} \# \{ \Omega_n \cap B(x_1, \epsilon_n) \} \right). \end{array}$$

We intuitively see that p>d is necessary if the constrain set is finite, i.e. $\max_{n\in\mathbb{N}}|\mathcal{I}_n|<+\infty$, is it sufficient?

No! Why not?

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This example turns out to be sharp: $\varepsilon_n^p n \to \infty$ implies ill-posedness and $\varepsilon_n^p n \to 0$ implies well-posedness.

Continuum Limit of *p*-Laplace Learning

Theorem (Slepčev and T., 17)

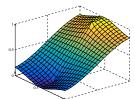
Let p > 1. Let u_n^* be a sequence of minimizers of $\mathcal{E}_n^{(p)}$ satisfying the $u_n^*(x_i) = \ell_i$ for all $i \in \mathcal{I}_n$ where $\max_{n \in \mathbb{N}} |\mathcal{I}_n| < +\infty$. Then, almost surely, the sequence (u_n^*, μ_n) is precompact in TL^p . The TL^p limit of any convergent subsequence, $(u_{n_m}^*, \mu_{n_m})$, is of the form (u, μ) where $u \in W^{1,p}(\Omega)$. Furthermore,

- (i) if $n\varepsilon_n^p \to 0$ as $n \to \infty$ then u is continuous and
 - (a) the whole sequence u_n^* converges to u both in TL^p and locally uniformly, meaning that for any Ω' with $\overline{\Omega'}\subset\Omega$

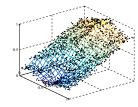
$$\lim_{n\to\infty}\max_{k\in\{1,\ldots,n\}:\,x_k\in\Omega'\}}|u(x_k)-u_n^*(x_k)|=0,$$

- (b) u is a minimizer of $\mathcal{E}_{\infty}^{(p)}$ with constraints;
- (ii) if $n\varepsilon_n^p \to \infty$ as $n \to \infty$ then u is constant.

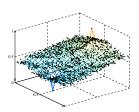
Numerical Comparisons



limit minimiser.

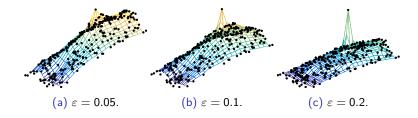


(a) p = 4 continuum (b) p = 4 minimiser (c) p = 2 minimiser

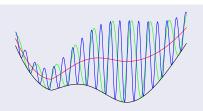


 $(\varepsilon = 0.06, n = 1280).$ $(\varepsilon = 0.06, n = 1280).$

Development of Spikes (p = 4)

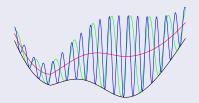


Variational Convergence



Green - \mathcal{E}_n , Blue - \mathcal{E}_m for m>n, Red - weak limit, Black - Γ -limit.

Variational Convergence

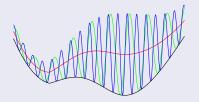


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We say $\mathcal{E}_{\infty} = \Gamma\text{-}\lim_n \mathcal{E}_n$, if for all u we have

- (i) $\forall u_n \to u$, $\mathcal{E}_{\infty}(u) \leq \liminf_{n \to \infty} \mathcal{E}_n(u_n)$;
- (ii) $\exists u_n \to u$, $\mathcal{E}_{\infty}(u) \geq \limsup_{n \to \infty} \mathcal{E}_n(u_n)$.

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Theorem

Let u_n be a sequence of almost minimizers of \mathcal{E}_n . If u_n are precompact and $\mathcal{E}_{\infty} = \Gamma\text{-lim}_n\,\mathcal{E}_n$ where \mathcal{E}_{∞} is not identically $+\infty$ then

$$\min \mathcal{E}_{\infty} = \lim_{n \to \infty} \inf \mathcal{E}_n.$$

Furthermore any cluster point of $\{u_n\}_{n=1}^{\infty}$ minimizes \mathcal{E}_{∞} .

1 Step 1: We show $\frac{1}{n^2 \varepsilon_n^p} \mathcal{E}_n^{(p)}(u_n) \approx \mathcal{E}_{\infty}^{(p)}(J_{\varepsilon_n} * \tilde{u}_n)$ where $\tilde{u}_n = u_n \circ T_n$ and J is a mollifier.

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- **2 Step 2:** We show $\operatorname{osc}_{\varepsilon_n}^{(n)}(u_n) \leq C \sqrt[p]{n\varepsilon_n^p\left(\frac{1}{n^2\varepsilon_n^p}\mathcal{E}_n^{(p)}(u_n)\right)}}$ where

$$\operatorname{osc}_{\varepsilon}^{(n)}(u_n)(x_k) = \max_{z \in B(x_k,\varepsilon) \cap \Omega_n} u_n(z) - \min_{z \in B(x_k,\varepsilon) \cap \Omega_n} u_n(z).$$

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Step 4: Γ -convergence of $\frac{1}{n^2 \varepsilon_n^p} \mathcal{E}_n^{(p)}$ to $\mathcal{E}_{\infty}^{(p)}$ plus a TL^p compactness result is now enough to get convergence of constrained minimizers.

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Proposition

Define $u_n^*(x) = \mathbb{E}[g^{\dagger}(B_{S(x)}^x)]$. Then u_n^* minimises $\mathcal{E}_n^{(2)}$ subject to the constraints.

9 Step 1: We show B_t^x behaves approximately as a Brownian motion and therefore

$$\mathbb{P}\left(\max_{t=1,\dots,k}|B_t^{\mathsf{X}}-\mathsf{X}|>\alpha\sqrt{k}\varepsilon\right)\leq e^{-c\alpha^2}.$$

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$$= \mathbb{E} \left[\left| g^{\dagger}(B_{S(x)}^{\times}) - g^{\dagger}(x) \right| \left| S(x) \leq k \right| \mathbb{P}(S(x) \leq k) \right|$$

$$+ \mathbb{E} \left[\left| g^{\dagger}(B_{S(x)}^{\times}) - g^{\dagger}(x) \right| \left| S(x) > k \right| \mathbb{P}(S(x) > k) \right]$$

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$$\begin{aligned} |u_n^*(x) - g^{\dagger}(x)| &\leq \mathbb{E} \left| g^{\dagger}(B_{S(x)}^x) - g^{\dagger}(x) \right| \\ &= \mathbb{E} \left[\left| g^{\dagger}(B_{S(x)}^x) - g^{\dagger}(x) \right| \left| S(x) \leq k \right] \mathbb{P}(S(x) \leq k) \right. \\ &+ \mathbb{E} \left[\left| g^{\dagger}(B_{S(x)}^x) - g^{\dagger}(x) \right| \left| S(x) > k \right] \mathbb{P}(S(x) > k) \right. \\ &\leq \alpha \mathrm{Lip}(g^{\dagger}) \sqrt{k\varepsilon} + 2 \|g^{\dagger}\|_{L^{\infty}} e^{-ck\beta}. \end{aligned}$$

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$$= \mathbb{E}\left[\left|g^{\dagger}(B_{S(x)}^{\mathsf{x}}) - g^{\dagger}(x)\right| \left|S(x) \leq k\right] \mathbb{P}(S(x) \leq k)\right]$$

$$+\mathbb{E}\left[\left|g^{\dagger}(B_{S(x)}^{x})-g^{\dagger}(x)\right|\left|S(x)>k\right]\mathbb{P}(S(x)>k)\right]$$

$$\leq \alpha \mathrm{Lip}(g^{\dagger}) \sqrt{k} \varepsilon + 2 \|g^{\dagger}\|_{L^{\infty}} e^{-ck\beta}.$$

Choosing
$$k = \frac{C}{\beta} \log \frac{\sqrt{\beta}}{\varepsilon}$$
 implies (with high probability) $|u_n^*(x) - g^{\dagger}(x)| \le C \frac{\varepsilon}{\sqrt{\beta}} \log \frac{\sqrt{\beta}}{\varepsilon}$.

Discrete variational problem: minimise

$$\mathcal{E}_{n}^{(2)}(u_{n}) = \sum_{i,j=1}^{n} w_{ij} |u_{n}(x_{i}) - u_{n}(x_{j})|^{2}$$
s.t. $u_{n}(x_{i}) = \ell_{i} \, \forall \, i \in \mathcal{I}_{n}$.

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$$L_n u_n^*(x_i) = 0$$
 for $i \notin \mathcal{I}_n$
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where

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Continuum variational problem: minimise

$$\mathcal{E}_{n}^{(2)}(u_{n}) = \sum_{i,j=1}^{n} w_{ij} |u_{n}(x_{i}) - u_{n}(x_{j})|^{2} \quad \mathcal{E}_{\infty}^{(2)}(u) = \sigma_{\eta} \int_{\Omega} \|\nabla u(x)\|^{2} \rho^{2}(x) dx$$
s.t. $u_{n}(x_{i}) = \ell_{i} \forall i \in \mathcal{I}_{n}$.
s.t. $u(x) = g^{\dagger}(x) \forall x \in \tilde{\Omega}$.

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• Euler-Lagrange equation:

$$\mathcal{L}u^*(x) = 0$$
 for $x \in \Omega \setminus \tilde{\Omega}$
 $u^*(x) = g^{\dagger}(x)$ for $x \in \tilde{\Omega}$
 $\frac{\partial u^*}{\partial n}(x) = 0$ for $x \in \partial \Omega$
where

where
$$\mathcal{L}u(x) = -\frac{1}{\rho(x)} \mathrm{div}(\rho^2 \nabla u)(x).$$

From Step 3, we have

$$\max_{x_i \in \widetilde{\Omega}} |u_n^*(x_i) - g^{\dagger}(x_i)| \le C \frac{\varepsilon}{\sqrt{\beta}} \log \frac{\sqrt{\beta}}{\varepsilon}$$

and now we need to extend the convergence to the whole domain.

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and now we need to extend the convergence to the whole domain.

9 Step 4: Pointwise convergence of the graph Laplacian.

Theorem (Calder, Slepčev and T. (2020))

There exists C>c>0 such that for any $\varphi\in C^3(\overline{\Omega})$ and any $\varepsilon\leq \vartheta\leq \frac{1}{\varepsilon}$,

$$\sup_{x \in \Omega_n} \left| L_n \varphi(x) - \mathcal{L} \varphi(x) + b.c.'s \right| \leq C \|\varphi\|_{C^3(\overline{\Omega})} (\varepsilon + \vartheta)$$

with probability at least $1 - Cne^{-cn\varepsilon^{d+2}\vartheta^2}$

Step 5: *u** solves

$$\left\{ egin{aligned} \mathcal{L}u^* &= 0 & & ext{in } \Omega \setminus ilde{\Omega} \ u^* &= g^\dagger & & ext{in } ilde{\Omega} \ rac{\partial u^*}{\partial n} &= 0 & & ext{on } \partial \Omega. \end{aligned}
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$$\left\{ egin{aligned} \mathcal{L}arphi &=1 & ext{in }\Omega\setminus ilde{\Omega} \ arphi &=0 & ext{in } ilde{\Omega} \ rac{\partial arphi}{\partial n} &=1 & ext{on }\partial \Omega. \end{aligned}
ight.$$

Step 5: *u*[∗] solves

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Let φ solve

$$egin{cases} \mathcal{L}arphi = 1 & ext{in } \Omega \setminus ilde{\Omega} \ arphi = 0 & ext{in } ilde{\Omega} \ rac{\partial arphi}{\partial n} = 1 & ext{on } \partial \Omega. \end{cases}$$

Then let

$$v = \left\{ \begin{array}{ll} u^* + M\vartheta\varphi & \text{in } \Omega \setminus \tilde{\Omega} \\ g^\dagger & \text{on } \tilde{\Omega}. \end{array} \right.$$

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By the max principle, and since $L_n(u_n^* - v) < 0$ on $\Omega \setminus \tilde{\Omega}$,

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Using the same argument on $v - u_n^*$ we have

$$\|u_n^* - v\|_{L^{\infty}(\Omega_n)} \leq \frac{C\varepsilon}{\sqrt{\beta}} \log \frac{\sqrt{\beta}}{\varepsilon}.$$

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Using the same argument on $v - u_n^*$ we have

$$\|u_n^* - v\|_{L^{\infty}(\Omega_n)} \leq \frac{C\varepsilon}{\sqrt{\beta}} \log \frac{\sqrt{\beta}}{\varepsilon}.$$

§ Step 7: Since $\|\varphi\|_{\mathrm{L}^{\infty}} \leq C$ then

$$\|u_n^* - u^*\|_{L^{\infty}(\Omega_n)} \leq \frac{C\varepsilon}{\sqrt{\beta}} \log \frac{\sqrt{\beta}}{\varepsilon}.$$

Large Data Limits for $|\mathcal{I}_n| \to \infty$

Theorem (Calder, Slepčev and T. (2020))

III-Posed Regime. Let ε_n satisfy a lower bound. Let u_n^* be a sequence of minimizers of $\mathcal{E}_n^{(2)}$ satisfying the constraints. Assume $\beta_n \ll \varepsilon_n^2$. Then, almost surely, $\{u_n^*\}_{n \in \mathbb{N}}$ is precompact and any convergent subsequence converges to a constant.

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Theorem (Calder, Slepčev and T. (2020))

Well-Posed Regime. Let ε_n satisfy a lower bound. Let u_n^* be a sequence of minimizers of $\mathcal{E}_n^{(2)}$ satisfying the constraints and u^* be the minimiser of $\mathcal{E}_\infty^{(2)}$ with constraints. Assume $\beta_n \gg \varepsilon_n^2$. Then, almost surely, u_n^* converges to u^* uniformly, in particular

$$\max_{i=1,\ldots,n} |u_n^*(x_i) - u^*(x_i)| \lesssim \frac{\varepsilon_n}{\sqrt{\beta_n}} \log \frac{\sqrt{\beta_n}}{\varepsilon_n}.$$

Contents

- Discrete-To-Continuum Topology
- 2 p-Laplace Learning
- Poisson Learning
- Fractional Laplace Learning
- Graph Neural Networks



1 Let us assume $\mathcal{I}_n = \{1, \ldots, m\}$.

Figure: A toy example with two labels which are seen as spikes.

¹Nadler, Srebro and Zhou, *Statistical Analysis of Semi-Supervised Learning*, NeurIPS, 2009, pp. 1330–1338

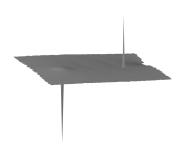


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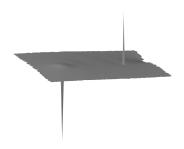


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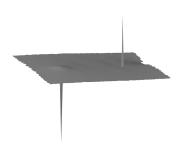


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- One way to correct this bias would be to consider $u_n^* c$, but this is just the solution Laplace Learning with the labels $\ell_i c$, why would we expect to do better with the the wrong label?

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Laplace Learning on MNIST

# Labels/class	1	2	3	4
Laplace	16.1 (6.2)	()	42.0 (12)	57.8 (12)
Graph NN	58.8 (5.6)		70.2 (4)	71.3 (2.6)

# Labels/class	5	10	50	100
Laplace	69.5 (12)	()	96.9 (0.1)	97.1 (0.1)
Graph NN	73.4 (1.9)		89.0 (0.5)	90.6 (0.4)

Average accuracy over 10 trials with standard deviation in brackets.

C.f. for 1 label per class the shifted Laplacian method achieves 85.9% accuracy.

Graph NN: 1-nearest neighbour using graph geodesic distance.

Random Walks at Low Labelling Rates

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- This means $B_{S(x)}^x$ is distributionally independent of x.
- **5** This implies u_n^* is approximately a constant on $\{x_i\}_{i \notin \mathcal{I}_n}$.
- The stationary distribution of B_t^x is $\pi(x_i) = \frac{d_i}{\sum_{j=1}^n d_j}$, so it follows that

$$u_n^*(x_i) = \mathbb{E}[\ell(B_{S(x)}^x)] \approx \frac{\sum_{i \in \mathcal{I}_n} d_i \ell_i}{\sum_{i \in \mathcal{I}_n} d_i} =: c$$

for all $i \notin \mathcal{I}_n$.

Laplace's Equation at Low Labelling Rates I

① Assume no labels are connected, i.e. $w_{ij} = 0$ for all $i, j \in \mathcal{I}_n$.

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$$L_n u_n^*(x_i) = \sum_{j=1}^n w_{ij} (u_n^*(x_i) - u_n^*(x_j))$$

$$\approx \sum_{j \notin \mathcal{I}_n} w_{ij} (\ell_i - c)$$

$$= d_i (\ell_i - c).$$

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$$= d_i (\ell_i - c).$$

We also have

$$\sum_{i=1}^n d_i u_n(x_i) \approx \sum_{i \in \mathcal{I}_n} d_i \ell_i + c \sum_{i \notin \mathcal{I}_n} d_i = c \sum_{i=1}^n d_i.$$

Laplace's Equation at Low Labelling Rates II

• For $|\mathcal{I}_n| \ll n$, u_n^* approximately satisfies

$$L_n u_n^*(x_i) \approx \sum_{j \in \mathcal{I}_n} d_j (\ell_j - c) \delta_{ij}, \qquad \frac{1}{\sum_{i=1}^n d_i} \sum_{i=1}^n d_i u_n^*(x_i) \approx c.$$

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• Shifting by c we could define v_n^* by

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• Shifting by c we could define v_n^* by

$$L_n v_n^*(x_i) = \sum_{j \in \mathcal{I}_n} d_j (\ell_j - c) \delta_{ij}, \qquad \sum_{i=1}^n d_i v_n^*(x_i) = 0.$$

• However, we find a slight improvement in performance if we additionally normalise each node and therefore we define v_n^* to satisfy

$$L_n v_n^*(x_i) = \sum_{j \in \mathcal{I}_n} (\ell_j - \bar{c}) \delta_{ij}, \qquad \sum_{i=1}^n v_n^*(x_i) = 0$$

where
$$\bar{c} = \frac{1}{|\mathcal{I}_n|} \sum_{i \in \mathcal{I}_n} \ell_i$$
.

Poisson Random Walk

Recall that B_t^x is the random walk starting from x and transitioning from x_i to x_j with probability proportional to w_{ij} .

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Theorem (Calder, Cook, Slepčev and T. (2020))

Let

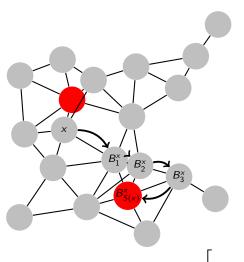
$$v_n^{(T)}(x_i) = \mathbb{E}\left[\frac{1}{d_i}\sum_{t=0}^T \sum_{j\in\mathcal{I}_n} (\ell_j - \bar{c})\mathbb{1}_{B_t^{x_j} = x_i}\right].$$

Then,

$$v_n^{(T+1)}(x_i) = v_n^{(T)}(x_i) + \frac{1}{d_i} \left(\sum_{j \in \mathcal{I}_n} (\ell_j - \overline{c}) \delta_{ij} - L_n v_n^{(T)}(x_i) \right)$$

and moreover $v_n^{(T)} \to v_n^*$ as $T \to \infty$.

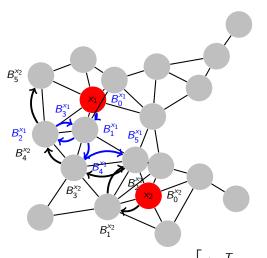
Laplace's Random Walk (Again)



Red - labelled nodes, grey unlabelled nodes.

$$u_n^*(x) = \mathbb{E}\left[\sum_{j\in\mathcal{I}_n} \ell_j \mathbb{1}_{B_{S(x)}^x = x_j}\right]$$

Poisson's Random Walk



Red - labelled nodes, grey unlabelled nodes.

Notice that

$$\begin{split} &\lim_{T \to \infty} \mathbb{E} \left[\frac{1}{d_i} \sum_{j \in \mathcal{I}_n} \ell_j \mathbb{1}_{B_t^{x_j} = x_i} \right] \\ &= \frac{m \overline{c}}{\sum_{j=1}^n d_j} \\ &= \lim_{T \to \infty} \mathbb{E} \left[\frac{\overline{c}}{d_i} \sum_{j \in \mathcal{I}_n} \mathbb{1}_{B_t^{x_j} = x_i} \right]. \end{split}$$

$$v_n^*(x) = \lim_{T \to \infty} \mathbb{E}\left[\frac{1}{d_i} \sum_{t=0}^T \sum_{j \in \mathcal{I}_n} (\ell_j - \bar{c}) \mathbb{1}_{B_t^{x_j} = x}\right].$$

MNIST Results

	# Labels per class				
	1	2	3	4	5
Laplace/LP	16.1 (6.2)	28.2 (10.3)	42.0 (12.4)	57.8 (12.3)	69.5 (12.2)
NN	55.8 (5.1)	65.0 (3.2)	68.9 (3.2)	72.1 (2.8)	74.1 (2.4)
Random Walk	66.4 (5.3)	76.2 (3.3)	80.0 (2.7)	82.8 (2.3)	84.5 (2.0)
MBO	19.4 (6.2)	29.3 (6.9)	40.2 (7.4)	50.7 (6.0)	59.2 (6.0)
VolumeMBO	89.9 (7.3)	95.6 (1.9)	96.2 (1.2)	96.6 (0.6)	96.7 (0.6)
WNLL	55.8 (15.2)	82.8 (7.6)	90.5 (3.3)	93.6 (1.5)	94.6 (1.1)
Centered Kernel	19.1 (1.9)	24.2 (2.3)	28.8 (3.4)	32.6 (4.1)	35.6 (4.6)
Sparse LP	14.0 (5.5)	14.0 (4.0)	14.5 (4.0)	18.0 (5.9)	16.2 (4.2)
p-Laplace	72.3 (9.1)	86.5 (3.9)	89.7 (1.6)	90.3 (1.6)	91.9 (1.0)
Poisson	90.2 (4.0)	93.6 (1.6)	94.5 (1.1)	94.9 (0.8)	95.3 (0.7)
PoissonMBO	96.5 (2.6)	97.2 (0.1)	97.2 (0.1)	97.2 (0.1)	97.2 (0.1)

Average (standard deviation) classification accuracy over 100 trials.

FashionMNIST Results

	# Labels per class					
	1	2	3	4	5	
Laplace/LP	18.4 (7.3)	32.5 (8.2)	44.0 (8.6)	52.2 (6.2)	57.9 (6.7)	
NN	44.5 (4.2)	50.8 (3.5)	54.6 (3.0)	56.6 (2.5)	58.3 (2.4)	
Random Walk	49.0 (4.4)	55.6 (3.8)	59.4 (3.0)	61.6 (2.5)	63.4 (2.5)	
MBO	15.7 (4.1)	20.1 (4.6)	25.7 (4.9)	30.7 (4.9)	34.8 (4.3)	
VolumeMBO	54.7 (5.2)	61.7 (4.4)	66.1 (3.3)	68.5 (2.8)	70.1 (2.8)	
WNLL	44.6 (7.1)	59.1 (4.7)	64.7 (3.5)	67.4 (3.3)	70.0 (2.8)	
Centered Kernel	11.8 (0.4)	13.1 (0.7)	14.3 (0.8)	15.2 (0.9)	16.3 (1.1)	
Sparse LP	14.1 (3.8)	16.5 (2.0)	13.7 (3.3)	13.8 (3.3)	16.1 (2.5)	
p-Laplace	54.6 (4.0)	57.4 (3.8)	65.4 (2.8)	68.0 (2.9)	68.4 (0.5)	
Poisson	60.8 (4.6)	66.1 (3.9)	69.6 (2.6)	71.2 (2.2)	72.4 (2.3)	
PoissonMBO	62.0 (5.7)	67.2 (4.8)	70.4 (2.9)	72.1 (2.5)	73.1 (2.7)	

Average (standard deviation) classification accuracy over 100 trials.

C.f. state-of-the-art clustering result of *67.2%* [McConville et al., 2019].

CIFAR-10 Results

	# Labels per class					
	1	2	3	4	5	
Laplace/LP	10.5 (1.3)	12.5 (4.4)	13.1 (3.8)	14.5 (4.7)	18.0 (6.9)	
NN	33.6 (4.4)	37.3 (3.3)	40.3 (3.0)	40.9 (2.7)	42.1 (2.4)	
Random Walk	37.1 (5.0)	42.1 (3.7)	45.8 (3.4)	47.0 (2.8)	48.8 (2.5)	
MBO	15.2 (4.1)	20.4 (4.8)	25.9 (4.1)	29.6 (4.3)	34.5 (4.2)	
VolumeMBO	40.3 (8.0)	47.2 (7.1)	52.2 (5.3)	53.3 (4.7)	55.9 (4.0)	
WNLL	20.8 (6.4)	34.5 (6.2)	42.1 (5.2)	46.1 (4.4)	50.2 (3.5)	
Centered Kernel	13.8 (1.1)	15.5 (1.2)	17.3 (1.4)	18.8 (1.7)	20.4 (1.6)	
Sparse LP	10.4 (2.1)	11.1(1.4)	11.8 (2.1)	12.8 (4.4)	13.6 (3.3)	
p-Laplace	28.7 (6.6)	39.8 (6.4)	45.7 (2.6)	46.8 (1.7)	50.4 (2.9)	
Poisson	41.6 (5.4)	46.9 (4.2)	51.1 (3.4)	52.5 (3.0)	54.5 (3.0)	
PoissonMBO	42.1 (7.0)	49.1 (5.3)	53.8 (4.4)	55.6 (3.7)	57.4 (3.4)	

Average (standard deviation) classification accuracy over 100 trials.

C.f. state-of-the-art clustering result of 41.2% [Mukherjee et al., ClusterGAN, CVPR 2019].

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The Fractional Graph Laplacian

• Let $(\lambda_i^{(n)}, q_i^{(n)})$ be the eigenvalues and eigenvectors of the normalised graph Laplacian $\frac{1}{n\varepsilon_n^2\sigma_n}L_n$.

The Fractional Graph Laplacian

- Let $(\lambda_i^{(n)}, q_i^{(n)})$ be the eigenvalues and eigenvectors of the normalised graph Laplacian $\frac{1}{n\varepsilon_n^2\sigma_n}L_n$.
- We define the fractional graph Laplacian energy $\mathcal{J}_n^{(\alpha,\tau)}$ by

$$\mathcal{J}_n^{(\alpha,\tau)}(u_n) = \sum_{i=1}^n \left(\lambda_i^{(n)} + \tau^2\right)^\alpha \langle u_n, q_i^{(n)} \rangle_{L^2(\mu_n)}^2.$$

The Fractional Graph Laplacian

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• When $\alpha = 1$ and $\tau = 0$,

$$\begin{split} \mathcal{J}_n^{(1,0)}(u_n) &= \sum_{i=1}^n \lambda_i^{(n)} \langle u_n, q_i^{(n)} \rangle_{\mathrm{L}^2(\mu_n)}^2 \\ &= \langle u_n, L_n u_n \rangle_{\mathrm{L}^2(\mu_n)} \\ &= \frac{1}{2} \mathcal{E}_n^{(2)}(u_n). \end{split}$$

Continuum Limit of the Graph Fractional Laplacian

• Let (λ_i, q_i) be the eigenvalues and eigenfunctions of the continuum operator \mathcal{L} .

Continuum Limit of the Graph Fractional Laplacian

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• When $\alpha=1$ and $\tau=0$ we have

$$\mathcal{J}_{\infty}^{(1,0)}(u) = \int_{\Omega} |\nabla u(x)|^2 \rho^2(x) \, \mathrm{d}x = \frac{1}{\sigma_n} \mathcal{E}_{\infty}^{(2)}(u).$$

Convergence of the Fractional Graph Laplacian

Theorem (Dunlop, Slepčev, Stuart and T. (2017))

Under assumptions on η , Ω , μ and a lower bound on $\epsilon_n \to 0$ we have, with probability one,

- **1** Γ- $\lim_{n\to\infty} 2\sigma_\eta \mathcal{J}_n^{(\alpha,\tau)} = \mathcal{J}_\infty^{(\alpha,\tau)}$ with respect to the TL^2 topology;
- ② if $\tau=0$, any sequence $\{u_n\}$ with $u_n:\Omega_n\to\mathbb{R}$ satisfying $\sup_n\|u_n\|_{L^2(\mu_n)}<\infty$ and $\sup_{n\in\mathbb{N}}\mathcal{J}_n^{(\alpha,0)}(u_n)<\infty$ is pre-compact in the TL^2 topology;
- **3** if $\tau > 0$, any sequence $\{u_n\}$ with $u_n : \Omega_n \to \mathbb{R}$ satisfying $\sup_{n \in \mathbb{N}} \mathcal{J}_n^{(\alpha,\tau)}(u_n) < \infty$ is pre-compact in the TL^2 topology.

Large Data Limits of Fractional Laplace Learning: III-Posed Case

Theorem (Dunlop, Slepčev, Stuart and T. (2017) and Weihs and T. (2023))

Assume $\varepsilon_n^{2\alpha} n \to \infty$ and $|\mathcal{I}_n| = m$ is fixed. Let $\{u_n^*\}_{n \in \mathbb{N}}$ be constrained minimisers of $\mathcal{J}_n^{(\alpha,\tau)}$. Assume $\sup_{n \in \mathbb{N}} \|u_n^*\|_{L^2(\mu_n)} < +\infty$. Then, with probability one, $\{u_n^*\}_{n \in \mathbb{N}}$ are precompact in TL^2 and any converging subsequence converges to a constant.

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• Remark 1: $\varepsilon_n^{2\alpha} n \to \infty$ is always true if $\alpha \le \frac{d}{2}$ (due to the lower bound on ε_n).

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- Remark 1: $\varepsilon_n^{2\alpha} n \to \infty$ is always true if $\alpha \le \frac{d}{2}$ (due to the lower bound on ε_n).
- Remark 2: The idea behind the proof is the same as in the p-Laplacian: measure the cost of a spike $u_n(x_i) = 1$ for i = 1 and $u(x_i) = 0$ otherwise.

Large Data Limits of Fractional Laplace Learning: Well-Posed Case

Theorem (Weihs and T. (2023))

Let $\Omega=[0,1]^d$ be the torus. Assume $\varepsilon_n^{\frac{\alpha-1}{2}}$ n is bounded, $\alpha>\frac{5d}{2}+4$ and $|\mathcal{I}_n|=m$ is fixed. Let $\{u_n^*\}_{n\in\mathbb{N}}$ be constrained minimisers of $\mathcal{J}_n^{(\alpha,\tau)}$. Then, with probability one, the sequence u_n^* converges uniformly to the constrained minimizer of $\mathcal{J}_\infty^{(\alpha,\tau)}$.

• As in the p-Laplacian case we want to control

$$u_n(x) - u_n(y) = \sum_{k=1}^n \langle u_n, q_k^{(n)} \rangle_{L^2(\mu_n)} \left(q_k^{(n)}(x) - q_k^{(n)}(y) \right).$$

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- For $k = K_n$ we use Weyl's law: $\lambda_{n,K_n}^{-1} \sim K_n^{-\frac{2}{d}} \sim \varepsilon_n$.

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- For $k=K_n$ we use Weyl's law: $\lambda_{n.K_n}^{-1} \sim K_n^{-\frac{2}{d}} \sim \varepsilon_n$.
- For $k = K_n, \ldots, n$ we use

$$\left| q_k^{(n)}(x) - q_k^{(n)}(y) \right| \lesssim \sqrt{n \mathcal{E}_n^{(2)}(q_k^{(n)})} |x - y| = \sqrt{n \lambda_k^{(n)}} |x - y|$$

to show that

$$\begin{split} \sum_{k=K_{n}}^{n} |\langle u_{n}, q_{k}^{(n)} \rangle_{L^{2}(\mu_{n})}| \left| q_{k}^{(n)}(x) - q_{k}^{(n)}(y) \right| &\leq \sqrt{n} |x - y| \sum_{k=K_{n}}^{n} \sqrt{\lambda_{k}^{(n)}} |\langle u_{n}, q_{k}^{(n)} \rangle_{L^{2}(\mu_{n})}| \\ &\lesssim n |x - y| \left(\sum_{k=1}^{n} \lambda_{k}^{(n)} |\langle u_{n}, q_{k}^{(n)} \rangle_{L^{2}(\mu_{n})}|^{2} \right)^{\frac{1}{2}} \\ &\leq n |x - y| \sqrt{\mathcal{J}_{n}^{(\alpha,0)}(u_{n})} (\lambda_{\nu}^{(n)})^{\frac{1-\alpha}{2}} \leq n \varepsilon^{\frac{\alpha-1}{2}} |x - y| \sqrt{\mathcal{J}_{n}^{(\alpha,0)}}. \end{split}$$

• For $k = 1, ..., K_n$ we can control

$$|\lambda_{n,k} - \lambda_k| \lesssim \lambda_k \left(\sqrt{\lambda_k} \varepsilon_n + \frac{d_{\mathcal{W}^{\infty}}(\mu_n, \mu)}{\varepsilon_n} \right)$$

 $\|q_i^{(n)}\|_{\mathcal{L}^{\infty}} \lesssim \lambda_k^{d+1}$

thanks to García Trillos, Gerlach, Hein and Slepčev (2020) and Calder, García Trillos and Lewicka (2022).

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Putting everything together implies

$$\frac{|u_n(x)-u_n(y)|}{|x-y|+d_{\mathrm{W}^{\infty}}(\mu_n,\mu)}\lesssim \sqrt{\mathcal{J}_n^{(\alpha,0)}(u_n)}(1+n\varepsilon_n^{\frac{\alpha-1}{2}})+\|u_n\|_{\mathrm{L}^2(\mu_n)}.$$

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Intuition on the Proof II

• For $k = 1, ..., K_n$ we can control

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- ullet Combined with the Γ -convergence result we can conclude the theorem.

Contents

- Discrete-To-Continuum Topology
- 2 p-Laplace Learning
- Poisson Learning
- Fractional Laplace Learning
- **5** Graph Neural Networks

Graph Diffusions

• Let $X(t) = [x_1(t)^\top, x_2(t)^\top, \dots, x_n(t)^\top]^\top \in \mathbb{R}^{n \times d}$ satisfy $rac{\mathrm{d} X}{\mathrm{d} t}(t) = \mathrm{div}(F(X(t), t) \odot \nabla X(t))$

where $F: \mathbb{R}^{n \times d} \times [0, \infty) \to \mathbb{R}^{n \times n}$ is a given function, ∇ is the graph gradient operator and div is the graph divergence operator.

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• Special case: Assume $[F(X,t)]_{ij}=\frac{1}{d_i}$ where $d_i=\sum_{j=1}^n w_{ij}$ then $\mathrm{d} X$

$$\frac{\mathrm{d}X}{\mathrm{d}t}(t) = -\tilde{L}_n X(t)$$

where $\tilde{L} = \operatorname{Id} - D^{-1}W = D^{-1}L_n$ is the random walk Laplacian.

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• Remark: This is the gradient flow corresponding to minimising a Dirichlet energy (without constraints). In particular, $x_i(t) \to c \in \mathbb{R}^d$, as $t \to \infty$, for all $i = 1, 2, \ldots, n$.

GRAND

GRAph Neural Diffusion (GRAND) networks were proposed by Chamberlain et. al.² as a architecture for graph neural networks.

The architecture is based on

$$X(T) = X(0) + \int_0^T \frac{\mathrm{d}X}{\mathrm{d}t}(t) \,\mathrm{d}t$$

where

$$\frac{\mathrm{d}X}{\mathrm{d}t}(t) = \mathrm{div}(F(X(t), t) \odot \nabla X(t))$$

and the parameter values that define F are to be learned.

²Chamberlain, Rowbottom, Gorinova, Bronstein, Webb and Rossi, *GRAND: Graph neural diffusion*, ICML, 2021, pp. 1407–1418.

Random Walk Viewpoint of GRAND

• We consider the (slightly modified) random walk B_t^x on $\{x_i(0)\}_{i=1}^n$

$$B_0^x = x \in \{x_i(0)\}_{i=1}^n$$

$$\mathbb{P}(B_{t+1}^x = x_j(0)|B_t^x = x_i(0)) = \begin{cases} 1 - \delta_t & \text{if } i = j\\ \frac{\delta_t W_{ij}}{d_i} & \text{if } i \neq j \end{cases}$$

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• Result: Let $X(t) = [x_1(t)^\top, x_2(t)^\top, \dots, x_n(t)^\top]^\top$ solve $X(0) = [\overline{x}_1^\top, \overline{x}_2^\top, \dots, \overline{x}_n^\top]^\top$ $X(k\delta_t) = X((k-1)\delta_t) - \delta_t \tilde{L}_n X((k-1)\delta_t).$

Then,

$$x_i(k\delta_t) = \mathbb{E}[B_k^{\overline{x}_i}].$$

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Then,

$$x_i(k\delta_t) = \mathbb{E}[B_t^{\overline{x}_i}].$$

• Result: As $k \to \infty$

$$x_i(k\delta_t) \to \tilde{x} := \sum_{i=1}^n \overline{x}_j \pi_j, \qquad \pi_j = \frac{d_j}{\sum_{i=1}^n d_i}.$$

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- Problem: In GRAND we suffer from the oversmoothing phenomena.
- Solution: Add a source term: let $Z(t) = [z_1(t)^\top, z_2(t)^\top, \dots, z_n(t)^\top]^\top \text{ solve}$ $\frac{\mathrm{d}z_i}{\mathrm{d}t}(t) = [\mathrm{div}(F(Z(t), t) \odot \nabla Z(t))]_i + \sum_{j \in \mathcal{I}_n} \delta_{ij} C_j$

where C_j is the source added at nodes $j \in \mathcal{I}_n$.

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We choose

$$\mathcal{C}_j = \overline{x}_j - \hat{x}, \qquad \hat{x} = \frac{1}{|\mathcal{I}_n|} \sum_{j \in \mathcal{I}_n} \overline{x}_j.$$

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 GRAph Neural Diffusion with source (GRAND++) is based on this architecture.

Random Walk Viewpoint of GRAND++

Assume that the initial condition satisfies

$$\sum_{i=1}^n z_i(0) = \sum_{i\in\mathcal{I}_n} \frac{1}{d_i} \left(\overline{x}_i - \hat{x} \right).$$

Random Walk Viewpoint of GRAND++

Assume that the initial condition satisfies

$$\sum_{i=1}^{n} z_i(0) = \sum_{i \in \mathcal{I}_n} \frac{1}{d_i} (\overline{x}_i - \hat{x}).$$

Theorem (T., Nguyen, Xia, Strohmer, Bertozzi, Osher and Wang (2021))

Let
$$Z(t) = [z_1(t)^{\top}, z_2(t)^{\top}, \dots, z_n(t)^{\top}]^{\top}$$
 solve

$$z_i(k\delta_t) = z_i((k-1)\delta_t) - \delta_t[\tilde{L}_n Z((k-1)\delta_t)]_i + \sum_{i \in \mathcal{I}_n} \delta_{ij}(\overline{x}_j - \hat{x}).$$

Then,

$$\left| z_i(k\delta_t) - \mathbb{E}\left[\sum_{s=0}^k \frac{1}{d_i} \sum_{j \in \mathcal{I}_n} (\overline{x}_j - \hat{x}) \mathbb{1}_{B_s^{\overline{x}_j} = \overline{x}_i} \right] \right| \to 0$$

as $k \to \infty$.

"Deep" Layer Results

	Depth	GRAND-nl	GRAND-nl-rw	GRAND++-nl	GRAND++-nl-rw
CORA	1 4 16 32	79.70 (1.88) 82.31 (0.91) 82.11 (1.42) 79.42 (0.64)	79.07 (3.05) 82.47 (1.32) 82.05 (1.31) 81.01 (0.81)	79.24 (1.48) 82.64 (0.89) 83.24 (0.20) 81.21 (0.37)	79.24 (1.48) 82.23 (1.14) 81.48 (1.07) 82.20 (1.15)
CiteSeer	1 16 64 128	71.84 (2.98) 72.65 (2.42) 70.29 (2.58) 65.19 (6.77)	71.84 (2.66) 73.06 (2.98) 69.65 (2.50) 65.45 (7.18)	70.45 (2.12) 72.48 (1.10) 72.64 (0.93) 74.24 (0.70)	71.74 (1.37) 73.29 (1.37) 73.38 (0.95) 74.23 (0.70)
PubMed	1 4 16	77.93 (1.27) 77.95 (1.28) 76.51 (2.73)	77.93 (1.26) 78.02 (1.14) 76.88 (2.57)	78.01 (0.68) 78.41 (0.88) 78.43 (0.78)	78.01 (0.68) 78.17 (0.93) 78.12 (0.87)

Table: Classification accuracy of GRAND and GRAND++ variants of different depth trained with 20 labels per class. (Unit: %)

Low Label Rate Results

Model	Labels/Class	CORA	CiteSeer	PubMed	CoauthorCS	Computer	Photo
GRAND++-I	1	54.94 (16.09)	58.95 (9.59)	65.94 (4.87)	60.30 (1.50)	67.65 (0.37)	83.12 (0.78)
	2	66.92 (10.04)	64.98 (8.31)	69.31 (4.87)	76.53 (1.85)	76.47 (1.48)	83.71 (0.90)
	5	77.80 (4.46)	70.03 (3.63)	71.99 (1.91)	84.83 (0.84)	82.64 (0.56)	88.33 (1.21)
	10	80.86 (2.99)	72.34 (2.42)	75.13 (3.88)	86.94 (0.46)	82.99 (0.81)	90.65 (1.19)
	20	82.95 (1.37)	73.53 (3.31)	79.16 (1.37)	90.80 (0.34)	85.73 (0.50)	93.55 (0.38)
GRAND-I	1	52.53 (16.40)	50.06 (17.98)	62.11 (10.58)	59.15 (5.73)	48.67 (1.66)	81.25 (2.50)
	2	64.82 (11.16)	59.55 (10.89)	69.00 (7.55)	73.83 (5.58)	74.77 (1.85)	82.13 (3.27)
	5	76.07 (5.08)	68.37 (5.00)	73.98 (5.08)	85.29 (2.19)	80.72 (1.09)	88.27 (1.94)
	10	80.25 (3.40)	71.90 (7.66)	76.33 (3.41)	87.81 (1.36)	82.42 (1.10)	90.98 (0.93)
	20	82.86 (2.39)	73.02 (5.89)	78.76 (1.69)	91.03 (0.47)	84.54 (0.90)	93.53 (0.47)
GCN	1	47.72 (15.33)	48.94 (10.24)	58.61 (12.83)	65.22 (2.25)	49.46 (1.65)	82.94 (2.17)
	2	60.85 (14.01)	58.06 (9.76)	60.45 (16.20)	83.61 (1.49)	76.90 (1.49)	83.61 (0.71)
	5	73.86 (7.97)	67.24 (4.19)	68.69 (7.93)	86.66 (0.43)	82.47 (0.97)	88.86 (1.56)
	10	78.82 (5.38)	72.18 (3.47)	72.59 (3.19)	88.60 (0.50)	82.53 (0.74)	90.41 (0.35)
	20	82.07 (2.03)	74.21 (2.90)	76.89 (3.27)	91.09 (0.35)	82.94 (1.54)	91.95 (0.11)
GAT	1	47.86 (15.38)	50.31 (14.27)	58.84 (12.81)	51.13 (5.24)	37.14 (7.81)	73.58 (8.15)
	2	58.30 (13.55)	55.55 (9.19)	60.24 (14.44)	63.12 (6.09)	65.07 (8.86)	76.89 (4.89)
	5	71.04 (5.74)	67.37 (5.08)	68.54 (5.75)	71.65 (4.53)	71.43 (7.34)	83.01 (3.64)
	10	76.31 (4.87)	71.35 (4.92)	72.44 (3.50)	74.71 (3.35)	76.04 (0.35)	87.42 (2.38)
	20	79.92 (2.28)	73.22 (2.90)	75.55 (4.11)	79.95 (2.88)	80.05 (1.81)	89.38 (2.48)
GraphSage	1	43.04 (14.01)	48.81 (11.45)	55.53 (12.71)	61.35 (1.35)	27.65 (2.39)	45.36 (7.13)
	2	53.96 (12.18)	54.39 (11.37)	58.97 (12.65)	76.51 (1.31)	42.63 (4.29)	51.93 (4.21)
	5	68.14 (6.95)	64.79 (5.16)	66.07 (6.16)	89.06 (0.69)	64.83 (1.62)	78.26 (1.93)
	10	75.04 (5.03)	68.90 (5.08)	70.74 (3.11)	89.68 (0.39)	74.66 (1.29)	84.38 (1.75)
	20	80.04 (2.54)	72.02 (2.82)	74.55 (3.09)	91.33 (0.36)	79.98 (0.96)	91.29 (0.67)
MoNet	1	47.72 (15.53)	39.13 (11.37)	56.47 (4.67)	58.99 (5.17)	23.78 (7.57)	34.72 (8.18)
	2	60.85 (14.01)	48.52 (9.52)	61.03 (6.93)	76.57 (4.06)	38.19 (3.72)	43.03 (8.22)
	5	73.86 (7.97)	61.66 (6.61)	67.92 (2.50)	87.02 (1.67)	59.38 (4.73)	71.80 (5.02)
	10	78.82 (5.38)	68.08 (6.29)	71.24 (1.54)	88.76 (0.49)	68.66 (3.30)	78.66 (3.17)
	20	82.07 (2.03)	71.52 (4.11)	76.49 (1.75)	90.31 (0.41)	73.66 (2.87)	88.61 (1.18)

Table: Classification accuracy of different GNNs trained with different number of labelled data per class (#per class) on six benchmark graph node classification tasks. (Unit: %)

Thank you for listening!

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In theory, there is no difference between theory and practice. But in practice, there is.

— Yogi Berra