

Bayesian Nonparametric Modelling with the Dirichlet Process Regression Smoother - Supplementary Material

J.E. Griffin and M. F. J. Steel

University of Kent and University of Warwick

Appendix A: Proofs

Proof of Proposition 1

Let $Z \sim H$. Then

$$\mathbb{E} [\mu_x^{(k)}] = \mathbb{E} \left[\sum_{i=1}^{\infty} p_i(x) \theta_i^k \right] = \mathbb{E}[Z^k] \sum_{i=1}^{\infty} \mathbb{E} [p_i(x)] = \mathbb{E}[Z^k].$$

Similarly, $\mathbb{E} [\mu_y^{(k)}] = \mathbb{E}[Z^k]$.

$$\begin{aligned} \mathbb{E} [\mu_x^{(k)} \mu_y^{(k)}] &= \mathbb{E} \left[\left(\sum_{i=1}^{\infty} p_i(x) \theta_i^k \right) \left(\sum_{i=1}^{\infty} p_i(y) \theta_i^k \right) \right] \\ &= \sum_{i=1}^{\infty} \mathbb{E} [p_i(x) p_i(y)] \mathbb{E} [\theta_i^{2k}] + \sum_{i=1}^{\infty} \sum_{j=1; j \neq i}^{\infty} \mathbb{E} [p_i(x) p_j(y)] \mathbb{E} [\theta_i^k] \mathbb{E} [\theta_j^k] \\ &= \mathbb{E} [Z^{2k}] \sum_{i=1}^{\infty} \mathbb{E} [p_i(x) p_i(y)] + \mathbb{E} [Z^k]^2 \left(1 - \sum_{i=1}^{\infty} \mathbb{E} [p_i(x) p_i(y)] \right) \\ &= \mathbb{E} [Z^k]^2 + \text{Var} [Z^k] \sum_{i=1}^{\infty} \mathbb{E} [p_i(x) p_i(y)] \end{aligned}$$

$$\text{Cov} (\mu_x^{(k)}, \mu_y^{(k)}) = \text{Var} [Z^k] \sum_{i=1}^{\infty} \mathbb{E} [p_i(x) p_i(y)]$$

and so

$$\text{Corr} (\mu_x^{(k)}, \mu_y^{(k)}) = \frac{\sum_{i=1}^{\infty} \mathbb{E} [p_i(x) p_i(y)]}{\sum_{i=1}^{\infty} \mathbb{E} [p_i(x)^2]}$$

which follows from the stationarity of $p_1(x), p_2(x), p_3(x), \dots$

Proof of Theorem 1

It is easy to show (see GS) that for any measurable set B

$$\text{Corr}(F_x(B), F_y(B)) = (M+1) \sum_{i=1}^{\infty} \mathbb{E}[p_i(x)p_i(y)]$$

In this case, if $x \notin S(\phi_i)$ or $y \notin S(\phi_i)$ then

$$\mathbb{E}[p_i(x)p_i(y)] = 0$$

Otherwise, let $R_i^{(1)} = \{j < i | x \in S(\phi_i) \text{ and } y \in S(\phi_i)\}$, $R_i^{(2)} = \{j < i | x \in S(\phi_i) \text{ and } y \notin S(\phi_i)\}$ and $R_i^{(3)} = \{j < i | x \notin S(\phi_i) \text{ and } y \in S(\phi_i)\}$

$$\begin{aligned} \mathbb{E}[p_i(x)p_i(y)] &= \mathbb{E} \left[V_i^2 \prod_{j \in R_i^{(1)}} (1 - V_i)^2 \prod_{j \in R_i^{(2)}} (1 - V_i) \prod_{j \in R_i^{(3)}} (1 - V_i) \right] \\ &= \frac{2}{(M+1)(M+2)} \mathbb{E} \left[\left(\frac{M}{M+2} \right)^{\#R_i^{(1)}} \left(\frac{M}{M+1} \right)^{\#R_i^{(2)}} \left(\frac{M}{M+1} \right)^{\#R_i^{(3)}} \right] \end{aligned}$$

and so

$$\text{Corr}(F_x(B), F_y(B)) = \frac{2}{M+2} \mathbb{E} \left[\sum_{i=1}^{\infty} B_i \left(\frac{M}{M+1} \right)^{\sum_{j=1}^{i-1} A_j} \left(\frac{M+1}{M+2} \right)^{\sum_{j=1}^{i-1} B_j} \right]$$

Proof of Theorem 2

$$\begin{aligned} &\mathbb{E} \left[\sum_{i=1}^{\infty} B_i \left(\frac{M}{M+1} \right)^{\sum_{j=1}^{i-1} A_j} \left(\frac{M+1}{M+2} \right)^{\sum_{j=1}^{i-1} B_j} \right] \\ &= \mathbb{E} \left[\sum_{\{i | y \in S(\phi_i) \text{ or } x \in S(\phi_i)\}} B_i \left(\frac{M}{M+1} \right)^{\sum_{j=1}^{i-1} A_j} \left(\frac{M+1}{M+2} \right)^{\sum_{j=1}^{i-1} B_j} \right] \end{aligned}$$

The set $\{i|y \in S(\phi_i) \text{ or } x \in S(\phi_i)\}$ must have infinite size since it is contained by the set $\{i|x \in S(\phi_i)\}$ which has infinite size. Let $\phi'_1, \phi'_2, \phi'_3, \dots$ be the subset of ϕ_1, ϕ_2, ϕ_3 for which $\{i|y \in S(\phi_i) \text{ or } x \in S(\phi_i)\}$ and define $B'_i = \mathbf{I}(y \in S(\phi'_i) \text{ and } x \in S(\phi'_i))$ then

$$\begin{aligned}
\text{Corr}(F_s, F_v) &= \frac{2}{M+2} \mathbf{E} \left[\sum_{i=1}^{\infty} B'_i \left(\frac{M}{M+1} \right)^i \left(\frac{M+1}{M+2} \right)^{\sum_{j=1}^{i-1} B'_j} \right] \\
&= \frac{2}{M+2} \sum_{i=1}^{\infty} \left(\frac{M}{M+1} \right)^i \mathbf{E}[B'_i] \prod_{j=1}^{i-1} \mathbf{E} \left[\left(\frac{M+1}{M+2} \right)^{B'_j} \right] \\
&= \frac{2}{M+2} \sum_{i=1}^{\infty} \left(\frac{M}{M+1} \right)^i p_{s,v} \left[\left(\frac{M+1}{M+2} \right) p_{s,v} + (1 - p_{s,v}) \right]^{i-1} \\
&= \frac{2}{M+2} \left(\frac{M}{M+1} \right) \sum_{i=0}^{\infty} \left(\frac{M}{M+1} \right)^i p_{s,v} \left[\left(\frac{M+1}{M+2} \right) p_{s,v} + (1 - p_{s,v}) \right]^i \\
&= \frac{2}{M+2} \left(\frac{M}{M+1} \right) p_{s,v} \frac{1}{1 - \left[\left(\frac{M}{M+2} \right) p_{s,v} + \frac{M}{M+1} (1 - p_{s,v}) \right]} \\
&= \frac{2 \frac{M}{M+2} p_{s,v}}{1 + \frac{M}{M+2} p_{s,v}}
\end{aligned}$$

Proof of Theorem 3

Since (C, r, t) follows a Poisson process on $\mathbb{R}^p \times \mathbb{R}_+^2$ with intensity $f(r)$, $p(C_k | s \in S(\phi_k) \text{ or } v \in S(\phi_k), r_k)$ is uniformly distributed on $B_{r_k}(s) \cup B_{r_k}(v)$ and $p(r_k | s \in S(\phi_k) \text{ or } v \in S(\phi_k)) = \frac{\nu(B_{r_k}(s) \cup B_{r_k}(v)) f(r_k)}{\int \nu(B_{r_k}(s) \cup B_{r_k}(v)) f(r_k) dr_k}$ where $\nu(\cdot)$ is Lebesgue measure. Then

$$\begin{aligned}
p_{s,v} &= P(s, v \in S(\phi_k) | s \in S_k \text{ or } v \in S(\phi_k)) \\
&= \int \int_{B_{r_k}(s) \cap B_{r_k}(v)} p(C_k, r_k | s \in S(\phi_k) \text{ or } v \in S(\phi_k)) dC_k dr_k \\
&= \frac{\int \nu(B_{r_k}(s) \cap B_{r_k}(v)) f(r_k) dr_k}{\int \nu(B_{r_k}(s) \cup B_{r_k}(v)) f(r_k) dr_k}.
\end{aligned}$$

Proof of Theorem 4

The autocorrelation function can be expressed as $f(p_{s,s+u})$ where $f(x) = 2 \frac{(M+1)}{(M+2)} / (1 + \frac{M}{M+2} x)$. Then by Faà di Bruno's formula

$$\frac{d^n}{du^n} f(p_{s,s+u}) = \sum \frac{n!}{m_1! m_2! m_3! \dots} \frac{d^{m_1 + \dots + m_n} f}{dp_{s,s+u}^{m_1 + \dots + m_n}} \prod_{\{j | m_j \neq 0\}} \left(\frac{d^j p_{s,s+u}}{du^j} \frac{1}{j!} \right)^{m_j},$$

where $m_1 + 2m_2 + 3m_3 + \dots + nm_n = n$ with $m_j \geq 0, j = 1, \dots, n$, and so

$$\lim_{u \rightarrow 0} \frac{d^n}{du^n} f(p_{s,s+u}) = \sum \frac{n!}{m_1!m_2!m_3! \dots} \lim_{u \rightarrow 0} \frac{d^{m_1+\dots+m_n} f}{dp_{s,s+u}^{m_1+\dots+m_n}} \prod_{\{j|m_j \neq 0\}} \left(\frac{d^j p_{s,s+u}}{du^j} \frac{1}{j!} \right)^{m_j}.$$

Since $\lim_{u \rightarrow 0} \frac{d^{m_1+\dots+m_n} f}{dp_{s,s+u}^{m_1+\dots+m_n}} = \lim_{p_{s,s+u} \rightarrow 1} \frac{d^{m_1+\dots+m_n} f}{dp_{s,s+u}^{m_1+\dots+m_n}}$ is finite and non-zero for all values of n , the degree of differentiability of the autocorrelation function is equal to the degree of differentiability of $p_{s,s+u}$. We can write $p_{s,s+u} = \left(\frac{4\mu}{a} - 1\right)^{-1}$ with $a = 2\mu_2 - uI$. Now $\frac{d^k p_{s,s+u}}{da^k} = (k-1)!(4\mu - a)^{-k}$ and $\lim_{u \rightarrow 0} \frac{d^k p_{s,s+u}}{da^k} = (k-1)!(2\mu)^{-k}$ which is finite and non-zero. By application of Faà di Bruno's formula

$$\frac{d^n}{du^n} p_{s,s+u} = \sum \frac{n!}{m_1!m_2!m_3! \dots} \frac{d^{m_1+\dots+m_n} p_{s,s+u}}{da^{m_1+\dots+m_n}} \prod_{\{j|m_j \neq 0\}} \left(\frac{d^j a}{du^j} \frac{1}{j!} \right)^{m_j}$$

and the degree of differentiability is determined by the degree of differentiability of a . If $p(r) \sim \text{Ga}(\alpha, \beta)$ then $\frac{d\mu_2}{du} = -\frac{1}{2} \left(\frac{u}{2}\right)^\alpha \exp\{-u/2\}$ and $\frac{dI}{du} = -\frac{1}{2} \left(\frac{u}{2}\right)^{\alpha-1} \exp\{-u/2\}$ and it is easy to show that $\frac{d^n a}{du^n} = C_n u^{\alpha-n+1} \exp\{-u/2\} + \zeta$ where ζ contains terms with power of x greater than $\alpha - n + 1$. If $\lim_{u \rightarrow 0} u^\alpha \exp\{-u/2\}$ is finite then so is $\lim_{u \rightarrow 0} u^{\alpha+k} \exp\{u/2\}$ for $k > 0$ and so the limit will be finite iff $\alpha - n + 1 \geq 0$, i.e. $\alpha \geq n - 1$.

Appendix B: Computational details

As we conduct inference on the basis of the Poisson process restricted to the set R , all quantities (C, r, t, V, θ) should have a superscript R . To keep notation manageable, these superscripts are not explicitly used in this Appendix.

Updating the centres

We update each centre C_1, \dots, C_K from its full conditional distribution Metropolis-Hastings random walk step. A new value C'_i for the i -th centre is proposed from $\text{N}(C_i, \sigma_C^2)$ where σ_C^2 is chosen so that the acceptance rate is approximately 0.25. If there is no x_i such that $x_i \in (C'_i - r_i, C'_i + r_i)$ or if there is one value of j such that $s_j = i$ for which $x_i \notin (C'_i - r_i, C'_i + r_i)$ then $\alpha(C_i, C'_i) = 0$. Otherwise, the acceptance probability has the form

$$\alpha(C_i, C'_i) = \frac{\prod_{j=1}^n \prod_{h < s_j} \text{and } C'_h - r_h < x_j < C'_h + r_h (1 - V_h)}{\prod_{j=1}^n \prod_{h < s_j} \text{and } C_h - r_h < x_j < C_h + r_h (1 - V_h)}.$$

Updating the distances

The distances can be updated using a Gibbs step since the full conditional distribution of r_k has a simple piecewise form. Recall that $d_{ik} = |x_i - C_k|$ and let $\mathcal{S}_k = \{j | s_j \geq k\}$. We define \mathcal{S}_k^{ord} to be a version of \mathcal{S}_k where the element have been ordered to be increasing in d_{ik} , i.e. if $i > j$ and $i, j \in \mathcal{S}_k^{ord}$ then $d_{ik} > d_{jk}$. Finally we define $d_k^* = \max[\{x_{\min} - C_k, C_k - x_{\max}\} \cup \{d_{ik} | s_i = k\}]$ and m^* be such that $x_i \in \mathcal{S}_k^{ord}$ and $x_{m^*} > d_k^*$ and $x_{m^*-1} < d_k^*$. Let l be the length of \mathcal{S}_k^{ord} . The full conditional distribution has density

$$f^*(z) \propto \begin{cases} f(z) & \text{if } d_k^* < z \leq d_{\mathcal{S}_k^{ord} m^* k} \\ f(z)(1 - V_k)^{i-m^*+1} & \text{if } d_{\mathcal{S}_k^{ord} i k} < z \leq d_{\mathcal{S}_k^{ord} i+1 k}, \quad i = m^*, \dots, l-1 \\ f(z)(1 - V_k)^{l-m^*+1} & \text{if } z > d_{\mathcal{S}_k^{ord} l k} \end{cases}$$

Swapping the positions of atoms

The ordering of the atoms should also be updated in the sampler. One of the K included atoms, say $(V_i, \theta_i, C_i, r_i)$, is chosen at random to be swapped with the subsequent atom $(V_{i+1}, \theta_{i+1}, C_{i+1}, r_{i+1})$. If $i < K$, the acceptance probability of this move is $\min\{1, (1 - V_{i+1})^{n_i} / (1 - V_i)^{n_{i+1}}\}$. If $i = K$, then a new point $(V_{K+1}, \theta_{K+1}, C_{K+1}, r_{K+1})$ is proposed from their prior and the swap is accepted with probability $\min\{1, (1 - V_{K+1})^{n_i}\}$.

Updating θ and V

The full conditional distribution of θ_i is proportional to $h(\theta_i) \prod_{\{j | s_j = i\}} k(y_j | \theta_i)$, where h is the density function of H . We update V_i from a Beta distribution with parameters $1 + \sum_{j=1}^n \mathbf{I}(s_j = i)$ and $M + \sum_{j=1}^n \mathbf{I}(s_j > i, |x_j - C_i| < r_i)$.

Updating M

This parameter can be updated by a random walk on the log scale. Propose $M' = M \exp(\epsilon)$ where $\epsilon \sim \mathcal{N}(0, \sigma_M^2)$ with σ_M^2 a tuning parameter chosen to maintain an acceptance rate close to 0.25. The proposed value should be accepted with probability

$$\frac{M'^{K+1} \left[\prod_{i=1}^K (1 - V_i) \right]^{M'} \beta(M')^{\alpha K} \exp \left\{ -\beta(M') \sum_{i=1}^K r_i \right\} p(M')}{M^{K+1} \left[\prod_{i=1}^K (1 - V_i) \right]^M \beta(M)^{\alpha K} \exp \left\{ -\beta(M) \sum_{i=1}^K r_i \right\} p(M)},$$

where $\beta(M)$ is β expressed as a function of M , as in our suggested form

$$\beta = \frac{2}{x^*} \log \left(\frac{1 + M + \varepsilon}{\varepsilon(M + 2)} \right).$$

Posterior inferences on $F_{\tilde{x}}$

We are often interested in inference at some point $\tilde{x} \in \mathcal{X}$ about the distribution $F_{\tilde{x}}$. We define $(\tilde{V}_1, \tilde{\theta}_1), (\tilde{V}_2, \tilde{\theta}_2), \dots, (\tilde{V}_J, \tilde{\theta}_J)$ to be the subset of $(V_1, \theta_1), (V_1, \theta_2) \dots, (V_K, \theta_K)$ for which $|\tilde{x} - C_i| < r_i$. Then

$$\begin{aligned} F_{\tilde{x}} = & \sum_{i=1}^J \delta_{\tilde{\theta}_i} \tilde{V}_i \prod_{j < i} (1 - \tilde{V}_j) \prod_{j \leq i} \prod_{l=1}^{n_j} (1 - V_l^{(j)}) + \prod_{i \leq J} \prod_{j=1}^{n_i} (1 - V_j^{(i)}) \sum_{l=J+1}^{\infty} \delta_{\tilde{\theta}_l} \tilde{V}_l \prod_{m < l} (1 - \tilde{V}_m) \\ & + \sum_{i=1}^N \sum_{j=1}^{n_i} \delta_{\theta_j^{(i)}} V_j^{(i)} \prod_{l < j} (1 - V_l^{(i)}) \prod_{l < i} (1 - V_l) \prod_{m=1}^{n_l} (1 - V_m^{(l)}) \end{aligned}$$

where n_j is a geometric random variable with success probability $1 - \tilde{p}$, $\theta_j^{(i)} \sim H$, $V_j^{(i)} \sim \text{Be}(1, M)$, $\tilde{\theta}_m \sim H$ and $\tilde{V}_m \sim \text{Be}(1, M)$ for $m > N$. We calculate \tilde{p} in the following way. If $x_{\min} < \tilde{x} < x_{\max}$, define i so that $x_{(i)} < \tilde{x} < x_{(i+1)}$, where $x_{(1)}, \dots, x_{(n)}$ is an ordered version of x_1, \dots, x_n , then $\tilde{p} = \frac{\beta}{2\alpha} \tilde{q}$ where

$$\begin{aligned} \tilde{q} = & (x_{(i+1)} - x_{(i)}) \mathcal{I} \left(\frac{x_{(i+1)} - x_{(i)}}{2} \right) + (x_{(i)} - \tilde{x}) \mathcal{I} \left(\frac{\tilde{x} - x_{(i)}}{2} \right) - (x_{(i+1)} - \tilde{x}) \mathcal{I} \left(\frac{x_{(i+1)} - \tilde{x}}{2} \right) \\ & - 2\mu^* \left(\frac{x_{(i+1)} - x_{(i)}}{2} \right) + 2\mu^* \left(\frac{\tilde{x} - x_{(i)}}{2} \right) + 2\mu^* \left(\frac{x_{(i+1)} - \tilde{x}}{2} \right) \end{aligned}$$

with $\mathcal{I}(y) = \int_0^y f(r) dr$ and $\mu^*(y) = \int_0^y r f(r) dr$. Otherwise if $\tilde{x} < x_{\min}$

$$\tilde{q} = 2\mu^* \left(\frac{x_{\min} - \tilde{x}}{2} \right) + (x_{\min} - \tilde{x}) \left(1 - \mathcal{I} \left(\frac{x_{\min} - \tilde{x}}{2} \right) \right)$$

and if $\tilde{x} > x_{\max}$

$$\tilde{q} = 2\mu^* \left(\frac{\tilde{x} - x_{\max}}{2} \right) + (\tilde{x} - x_{\max}) \left(1 - \mathcal{I} \left(\frac{\tilde{x} - x_{\max}}{2} \right) \right).$$

We use a truncated version of $F_{\tilde{x}}$ with h elements which are chosen so that $\sum_{i=1}^h p_i = 1 - \epsilon$ where ϵ is usually taken to be 0.001.

Model 2

This section is restricted to discussing the implementation when $m(x)$ follows a Gaussian process prior where we define $P_{ij} = \rho(x_i, x_j)$. We also reparametrise from u_i to $\phi_i = \sigma^2 \psi_i$.

Updating $\psi_i | s$

The full conditional distribution has the density

$$p(\phi_i) \propto \phi_i^{0.5(1-\sum \mathbf{I}(s_j=i, 1 \leq j \leq n))} \exp\{-0.5\phi_i/\sigma^2\}, \quad \phi_i > \phi_{min}$$

where $\phi_{min} = \max \{(y_i - m(x_i))^2 | s_j = i, 1 \leq j \leq n\}$. A rejection sampler for this full conditional distribution can be constructed using the envelope

$$h^*(\phi_i) \propto \begin{cases} \phi_i^{0.5(1-\sum \mathbf{I}(s_j=i, 1 \leq j \leq n))} & \phi_{min} < \phi_i < z \\ z^{0.5(1-\sum \mathbf{I}(s_j=i, 1 \leq j \leq n))} \exp\{-0.5(\phi_i - z)/\sigma^2\} & \phi_i > z \end{cases}$$

which can be sampled using inversion sampling. The acceptance probability is

$$\alpha(\phi_i) = \begin{cases} \exp\{-0.5(\phi_i - \phi_{min})/\sigma^2\} & \phi_{min} < \phi_i < z \\ \left(\frac{\phi_i}{z}\right)^{0.5-0.5k} \exp\{-0.5(z - \phi_{min})/\sigma^2\} & \phi_i > z \end{cases}$$

and the choice $z = \sigma^2 \sum \mathbf{I}(s_j = i, 1 \leq j \leq n)$ maximizes the acceptance rate.

Updating σ^{-2}

Using the prior $\text{Gamma}(\nu_1, \nu_2)$, the full conditional distribution of σ^{-2} is again a Gamma distribution, where we define $P = (P_{ij})$

$$\sigma^{-2} \sim \text{Ga} \left(\nu_1 + \frac{3K}{2} + \frac{n}{2}, \nu_2 + \frac{1}{2} \sum_{i=1}^K \phi_i + \frac{1}{2\omega} m(x)^T P^{-1} m(x) \right).$$

Updating $m(x_1), \dots, m(x_n)$

It is possible to update $m(x_i)$ using its full conditional distribution. However this tends to lead to slowly mixing algorithms. A more useful approach uses the transformation $m(x) = C^* z$ where C^* is the Cholesky factor of $\sigma_0^{-2} P^{-1}$, where $z \sim \text{N}(0, I)$. We then update z_j using their full conditional distribution which is a standard normal distribution truncated to the region $\cap_{i=1}^n (y_i - \sum_{k \neq j} C_{ik} z_k - \sqrt{\phi_i}, y_i - \sum_{k \neq j} C_{ik} z_k + \sqrt{\phi_i})$.

Updating ω

We define $\omega^2 = \sigma^2/\sigma_0^2$. If ω^2 follows a Gamma distribution with parameters a_0 and b_0 then the full conditional of σ_0^{-2} follows a Gamma distribution with parameters $a_0 + n/2$ and $b_0 + \sigma^{-2}m(x)^T P^{-1}m(x)/2$. A similar updating occurs for the Generalized inverse Gaussian prior used here.

Updating the Matèrn parameters

We update any parameters of the Matèrn correlation structure by a Metropolis-Hastings random walk. The full conditional distribution of the parameters (ζ, τ) would be proportional to

$$|P|^{-1/2} \exp \left\{ -\sigma^{-2}\omega^{-2}m(x)^T P^{-1}m(x) \right\} p(\zeta, \tau).$$