

Advanced Economic Theory
Models of Elections
Lecture 3

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Aggregate uncertainty and policy-motivated candidates

- . I consider a probabilistic voting model with aggregate uncertainty and policy motivated candidates.
- . In unique symmetric equilibrium, candidates' platforms diverge.
- . If voters update their preferences during campaigns, they are all ex ante better off when parties diverge to some extent.
- . Voters are better off with moderate policy-motivated candidates than with office-motivated candidates.
- . This is in contrast with models where voters preferences are fixed.

Value of platform divergence

- . Each voter j with bliss point $b_j \in \mathbb{R}$ has utility $L(|b_j - x|)$, with $L' < 0$, $L'' < 0$, and $\lim_{z \downarrow 0} L'(z) = 0$, $\lim_{z \uparrow \infty} L'(z) = -\infty$.
- . The ideal point b_j is decomposed as: $b_j = m + \delta_j + \varepsilon_j$:
 - . δ_j is the fixed j 's bias relative to the median platform m , the distribution of δ_j has compact support and zero median,
 - . ε_j is i.i.d. with $E[\varepsilon_j] = 0$, symm. density on compact support.
 - . m is the random median platform, with c.d.f. F and median μ .
- . Assume that F is symmetric and $\mu = 0$.
- . Consider divergent platforms $x_L = -x$ and $x_R = x$, with $x \geq 0$.
- . Platform x_L wins if and only if $m < \frac{x_L + x_R}{2} = 0$.

. The expected welfare of voter j is:

$$\begin{aligned}
 W_j(x) &= \int_{-\infty}^0 L(|m + \delta_j + \varepsilon_j - x_L|) f(m) dm \\
 &\quad + \int_0^{\infty} L(|m + \delta_j + \varepsilon_j - x_R|) f(m) dm \\
 &= \int_0^{\infty} [L(|-m - \delta_j - \varepsilon_j + x|) + L(|m + \delta_j + \varepsilon_j - x|)] f(m) dm.
 \end{aligned}$$

$W_j(x)$ is concave as it is the sum of integrals of concave functions.

Proposition There exists a welfare-improving threshold $\bar{x} > 0$ such that $W_j(x) > W_j(0)$ for all voters j whenever $0 < x < \bar{x}$.

Proof: Compare the difference one m at a time:

$$\begin{aligned}
 &L(|\delta_j + \varepsilon_j - (m - x)|) + L(|\delta_j + \varepsilon_j - (-m + x)|) \\
 &\text{vs. } L(|\delta_j + \varepsilon_j - m|) + L(|\delta_j + \varepsilon_j - (-m)|)
 \end{aligned}$$

. This is equivalent to comparing two lotteries with fixed $\delta_j + \varepsilon_j$:

even chance on $-m + x, m - x$ and even chance on $-m, m$.

. Clearly, when $x < m$, policy convergence is a mean-preserving spread of divergence at $-x$ and x ... and voter j is better off.

. For all δ_j, ε_j in the (compact) supports, $\frac{\partial W_j}{\partial x}(x)|_{x=0} > 0$.

. By strict concavity, there is unique $x(\delta, \varepsilon) > 0$ such that $W_j(0) = W_j(x)$ and by continuity $\bar{x} = \min_{\delta, \varepsilon} \{x(\delta, \varepsilon)\} > 0$.

. The aggregate voter welfare W^* is strictly concave:

$$W^*(x) = \int_{\delta, \varepsilon} \int_0^\infty [L(|-m - \delta_j - \varepsilon_j + x|) + L(|m + \delta_j + \varepsilon_j - x|)] dF(m) dH(\delta, \varepsilon).$$

Proposition A first-order stochastic increase in $f(\cdot | m > 0)$ induces an increase in the welfare-maximizing platform x^* .

Sketch of proof: For a greater spread in f , welfare is maximized by reducing payoff of moderate m and increasing payoff of extreme m .

Quadratic-normal case

- . Assume L is quadratic, i.e., $L(z) = -z^2$.
- . Say m is distributed normally with mean zero and variance σ^2 .
- . For each voter δ, ε , simplification yields:

$$W_{\delta, \varepsilon}(x) = -2 \int_0^{\infty} (x - m)^2 dF(m) - (\delta + \varepsilon)^2 = W_{0,0}(x) - (\delta + \varepsilon)^2.$$

- . By mean-variance analysis, $W^*(x)$ is a quadratic fcn:

$$\begin{aligned} W^*(x) &= - \int_{\delta, \varepsilon} [2 \int_0^{\infty} (x - m)^2 dF(m) + (\delta + \varepsilon)^2] dH(\delta, \varepsilon) \\ &= -2E[(x - m)^2 | m > 0] - E[(\delta + \varepsilon)^2] \\ &= -2(x - E[m | m > 0])^2 - V[m | m > 0] - V[\delta] - V[\varepsilon]. \end{aligned}$$

- . The social optimum is then $x^* = E[m | m > 0] = \sigma \sqrt{2/\pi}$.
- . As W^* is symmetric around x^* , $\bar{x} = 2E[m | m > 0] = 2\sigma \sqrt{\frac{2}{\pi}}$.

Model and equilibrium

- . Candidates L and R have ideal points $-b$ and $b > 0$.
- . Office benefit $w \in \mathbb{R}_+ \cup \{\infty\}$.
- . Pure policy motivation is $w = 0$, pure office is $w = \infty$.
- . Candidate R 's payoff from (x_L, x_R) is
$$\Pr(L \text{ wins})L(|b - x_L|) + \Pr(R \text{ wins})(L(|b - x_R|) + w).$$
- . We focus on symmetric, pure strategy equilibria.
- . We assume the hazard rate $\frac{f(m)}{1-F(m)}$ is weakly decreasing.
- . Let \bar{b} be the unique solution to $L'(b) = -wf(0)$.

Proposition There is a unique symmetric equilibrium, $(-x^e, x^e)$, and this equilibrium satisfies $0 \leq x^e < b$. If $b \leq \bar{b}$, then $x^e = 0$; and if $b > \bar{b}$, then x^e is the unique solution of the f.o.c.:

$$-L'(b-x) = [L(b-x) + w - L(x+b)]f(0).$$

Proof: Suppose $x_L = -x$. Candidate R 's payoff for $x_R \geq 0$ is:

$$F\left(\frac{x_R - x}{2}\right)L(b+x) + [1 - F\left(\frac{x_R - x}{2}\right)](L(b-x_R) + w).$$

- . Differentiating w.r.t. x_R and setting $x_R = x$ we obtain the f.o.c.
- . The s.o.c. is satisfied as $\frac{f(m)}{1-F(m)}$ is weakly decreasing.
- . Rearranging the f.o.c., I obtain: $\frac{L'(b-x)}{L(b+x) - L(b-x) - w} = f(0)$.
- . LHS is strictly decreasing in $x \in [0, b)$ by strict concavity of L : by intermediate value theorem, the solution $x^e \in (0, b)$.

Proposition Say L is a power function $L(z) = -z^\alpha$ with $\alpha > 1$. If $b > \bar{b}$, then $\frac{\partial x^e}{\partial b} > 0$, $\frac{\partial x^e}{\partial f(0)} < 0$, $\frac{\partial x^e}{\partial w} < 0$.

. Platform divergence increases as parties are more polarized, likelihood of electoral tie decreases, office benefits decrease.

. The limiting properties of equilibria are as follows:

. If $w = 0$, then x^e is a solution of $\frac{L'(b-x)}{L(b+x)-L(b-x)} = f(0)$.

. If $w \geq -\frac{L'(b)}{f(0)}$, then $x^e = 0$

. If $f(0) \rightarrow 0$, then $x^e \rightarrow$ solution of $\frac{L'(b-x)}{L(b+x)-L(b-x)-b} = 0$

. If $f(0) \rightarrow \infty$, then $x^e \rightarrow 0$

. If $b \rightarrow 0$, then $x^e \rightarrow 0$

. If L is a power function, then as $b \rightarrow \infty$, we have $x^e \rightarrow \frac{1}{2f(0)}$.

- . We now turn to relating voter welfare to candidates' ideologies.
- . Let \bar{b} be the ideology such that the equilibrium platform $x^e = \bar{x}$
- . If $0 \leq b \leq \bar{b}$, then platforms converge at zero.
- . If $\bar{b} < b < \bar{\bar{b}}$, then the ex ante welfare of all voters is higher with policy-motivated candidates than with platform convergence.
- . If $b > \bar{\bar{b}}$, then ex ante welfare of some voters is strictly lower.

Proposition In the quadratic-normal model, $\bar{\bar{b}} = \infty$:

$$\lim_{b \rightarrow \infty} x^e = \frac{1}{2f(0)} = \sigma \sqrt{\frac{\pi}{2}} < 2\sigma \sqrt{\frac{2}{\pi}} = 2E[m|m > 0] = \bar{x}.$$

- . All voters are always better off with policy-motivated candidates.

Policy preferences and effort (Callander, 2008)

- . There is no aggregate voter preference uncertainty.
- . All voters benefit from policy-makers' effort, regardless of their ideology.
- . Policy-motivated candidates care more about policies than opportunistic ones.
- . Opportunistic candidates converge to the median policy.
- . Policy-motivated candidates commit to their ideal policies.
- . They exert effort when in office to implement their ideal policies.
- . Voters anticipate this, and elect policy-motivated politicians despite their divergent platforms because they benefit from effort.

The model

- . There are n voters, n odd, and two candidates, L and R .
- . Each candidate i commits to a platform $x_i \in \mathbb{R}$.
- . The winner of the election, W , receives a benefit w and chooses a level of effort, $e_W \in [0, 1]$ at cost ce_W^2 .
- . Voters and candidates' payoffs depend on policy (x_W, e_W) .
- . All voters payoffs increase in effort e_W , but the payoffs of x_W differ because of ideological preferences.
- . Each voter j 's bliss point is b_j , the median voter's is $b_m = 0$.
- . Each voter $j \in \{1, 2, \dots, n\}$ utility is given by:
$$U_j(x_W, e_W) = -t_W[(b_j - x_W)^2 + (1 - e_W)^2].$$

- . The candidates' bliss points are $b_L = -b$ and $b_R = b > 0$.
- . Each candidate i 's effort type $t_i \in \{\ell, h\}$ is private information, with $0 < \ell < h$ and $\Pr\{t_i = \ell\} = q$.
- . The utility of candidate j is given by:

$$U_j(x_W, e_W | t_i) = -t_i[(b_j - x_W)^2 + (1 - e_W)^2] \\ + [w - c(e_W)^2] \Pr(W = j).$$
- . Voters' equilibrium beliefs on the candidates' types coincide, based on the observed platform x_L, x_R .
- . Each votes for the candidate who maximizes her expected utility.

Equilibrium Analysis

Lemma In equilibrium, the effort level of the elected candidate is $t_W / (t_W + c)$ for all t_W .

Lemma If $q \in \{0, 1\}$, a unique equilibrium exists in which both candidates L and R locate at the median voter's ideal point.

Lemma In every equilibrium: office-motivated candidates win with weakly higher probability, policy-motivated candidates locate weakly closer to their ideal point.

Lemma For $q \in (0, 1)$: if a pooling equilibrium exists, then L locates at $-b$ and R locates at b .

- . Let $b_1 > 0$ solve $(1 - \frac{\ell}{\ell+c})^2 = \frac{b_1^2}{1-q} + (1 - \frac{h}{h+c})^2$.
- . Median voter is indifferent between $x_R = b_1$ with $\Pr(t_i|x_R) = q$ and $x_L = 0$ knowing L is office motivated and exerts low effort.

Theorem Suppose $q \in (0, 1)$. For all $b \in [0, b_1]$, a unique equilibrium exists and is pooling: candidate L locates at $-b$ and candidate R locates at b irrespective of their types. A pooling equilibrium does not exist if $b > b_1$.

Proof: For $b < b_1$, median voter prefers a high-effort candidate with platform b , to a low-effort candidate with platform 0.

- . Policy-motivated candidates locate at bliss point b and then exert high effort.
- . Office-motivated candidates mimic their platform not to lose the election, but then provide low effort.

. Let b_2 solve $(1 - \frac{\ell}{\ell+c})^2 = b_2^2 + (1 - \frac{h}{h+c})^2$.

. Median voter is indifferent between $x_R = b_2$ knowing R is policy motivated and exerts high effort, and $x_L = 0$ knowing L is office motivated and exerts low effort.

Theorem Suppose $q \in (0, 1)$. For all $b \in (b_1, b_2)$, a unique equilibrium exists and is semi-separating: policy-motivated candidates L and R locate at $-b$ and b , and office motivated candidates mix over $-b$ and 0 , and over b and 0 respectively.

Theorem Suppose $q \in (0, 1)$. For all $b \geq b_2$, a unique equilibrium exists and is separating: policy-motivated candidates L and R locate at $-b$ and b , and office motivated candidate at 0 .

Proofs: For $b > b_2$, the median voter prefers a low-effort candidate with platform 0 to a high-effort candidate with platform b .

- . Office-motivated candidates locate at platform 0 to win the election and then provide low effort.
- . Policy-motivated candidates still locate at bliss point b . They care about policy too much to mimic office-motivated candidates.
- . For $b_1 < b < b_2$, neither pooling nor separating equilibrium exist. Equilibrium requires office-motivated candidates to mix.
- . In conclusion:
 - . policy motivated candidates choose divergent platforms;
 - . but they may still get elected as platform divergence signal that they care about policy,
 - . and so that they intend to exert effort when in office.

Summary

- . I have introduced candidates with policy preferences in the aggregate uncertainty model.
- . Because of uncertainty, equilibrium platforms diverge.
- . If voters' preferences may change during campaigns, then platform divergence improves electorate welfare.
- . I have presented a model without voter preference uncertainty, in which policy-motivated candidates diverge from median.
- . By diverging, candidates signal they care about policy and will exert effort if elected.

Next Lecture

- . I will consider how well elections aggregate information.
- . I present a model where voters have different information about candidates' valence.
- . I show that there exists an equilibrium in which informed non-partisan voters are pivotal, and the “best” candidate is elected.
- . I present a model with candidates more informed than voters.
- . Electoral competition induces candidates to convey some information to voters, but fails to achieve informational efficiency.
- . The electorate welfare loss is as severe as if only one candidate's information were efficiently revealed.