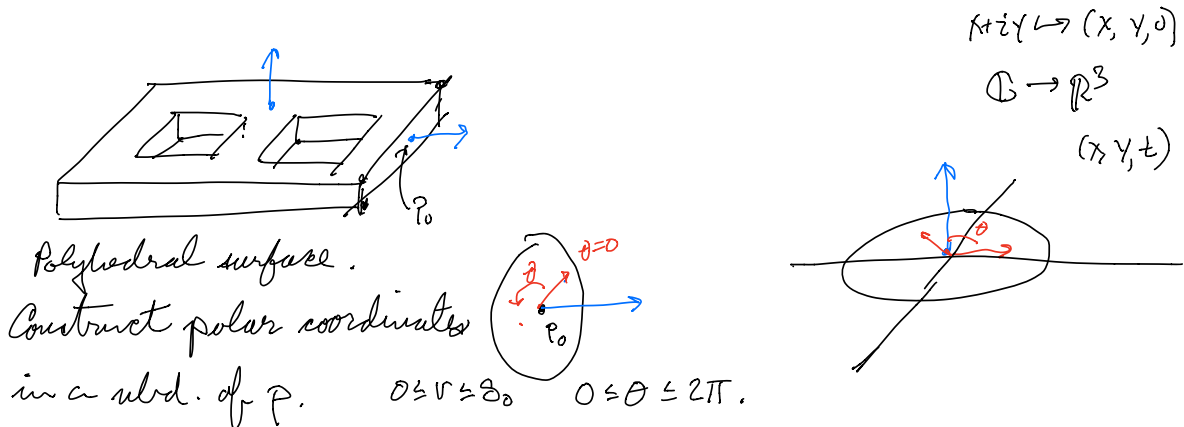


Polyhedron in  $\mathbb{R}^3$  is a topological surface consisting of faces, edges and vertices.

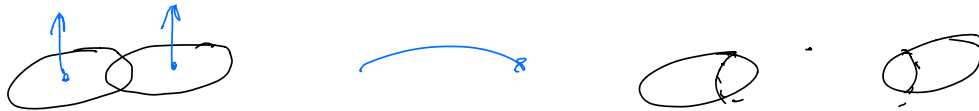
We will show that a polyhedron determines a Riemann surface. This construction gives a large number of examples (unlike previous constructions) including examples of Riemann surface structures on oriented surfaces of every genus. These constructions each have a finite # of parameters that can be adjusted.

Step 1. We will start by constructing charts at interior points of faces.

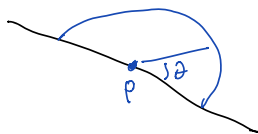
Our surface comes with an outward pointing unit normal.



If two points are in the same face then disks can overlap and transition functions have the form  $z \mapsto z+c$



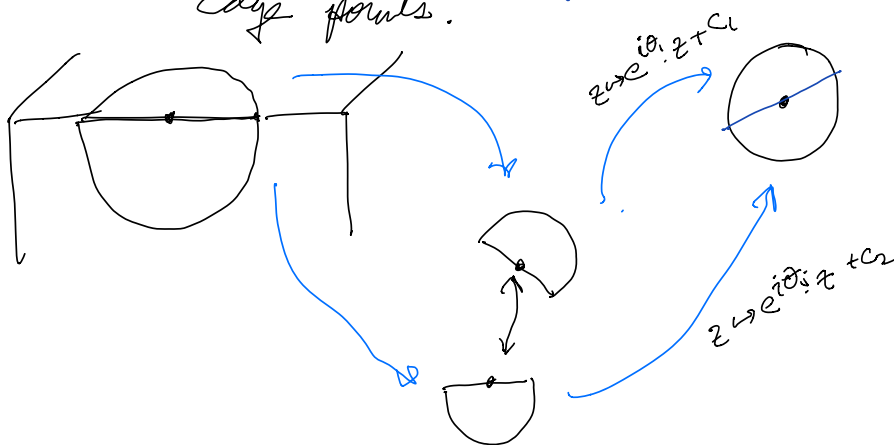
### Step 2, Coordinates on edges



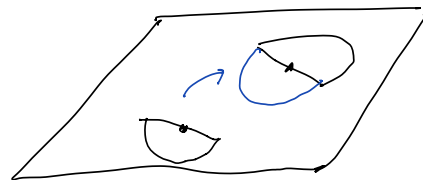
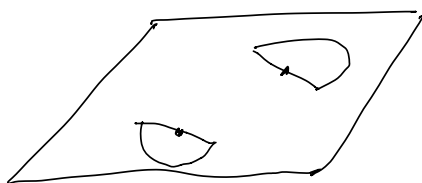
Let a point  $p$  on the boundary of a face  $f_i$  we can construct a half-disk coordinate.  
 $0 \leq r \leq S_p$   
 $0 \leq \theta \leq \pi$ .  
 half-disk coordinate.

If we "put together" a pair of these maps we get a disk coordinate.

Edge points.



Decide which half-disk becomes the upper half and which the lower half.



At this point we have an atlas for  $P$ -vertices where all of the transition maps have the form  $\phi_{jk}(z) \mapsto e^{2\pi i} z + c_{jk}$ . This is a holomorphic atlas of a special form and we will see this again.

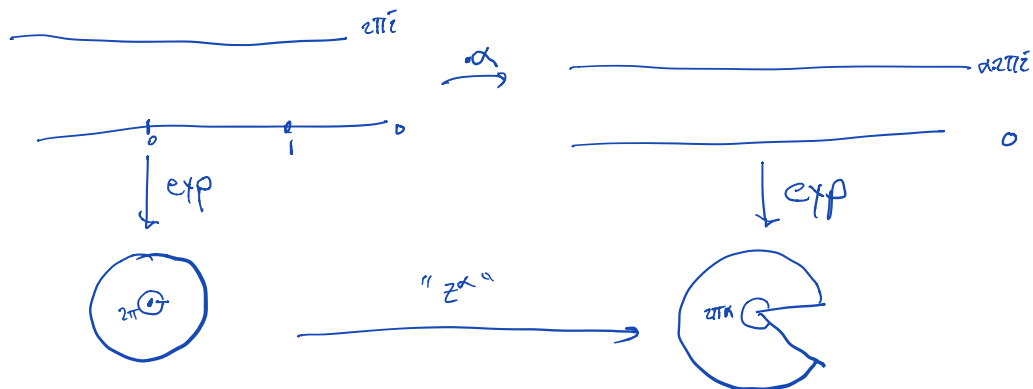
Step 3. Coordinates at vertices.

Remarks about the function  $z \mapsto z^\alpha$ .

We can make sense of this by writing

$$z^\alpha = \exp(\log z^\alpha) = \exp(\alpha \log z).$$

We interpret this by choosing a branch of the logarithm. Now let's assume that  $\alpha$  is real and positive. We get the following picture:

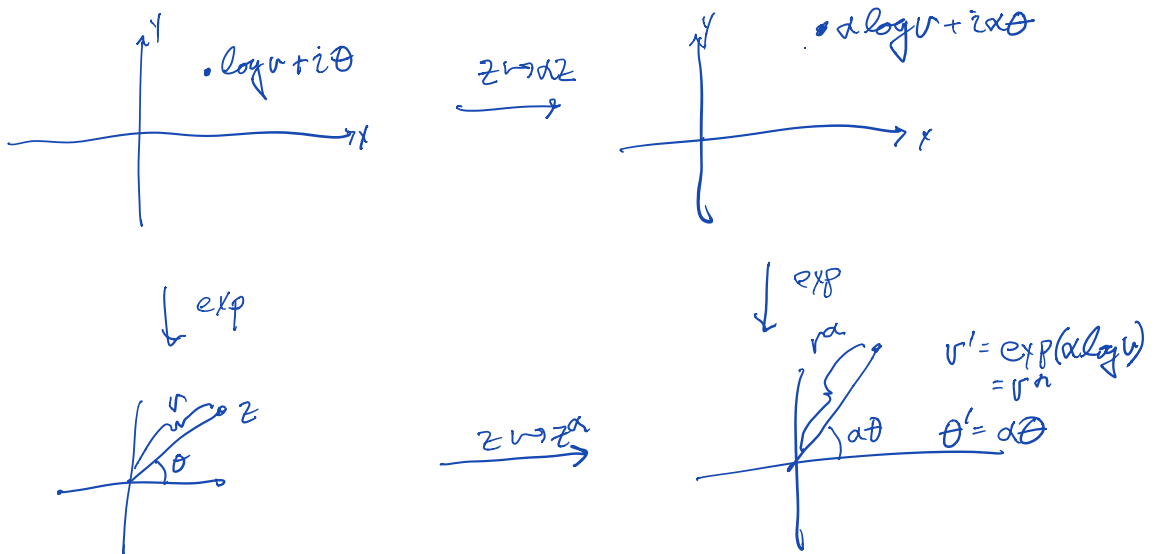


Choosing a different branch of the logarithm changes the lift of the map by a multiple of  $2\pi i$  and changes the map by a rotation of  $\exp(2\pi i k)$ .

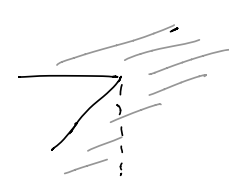
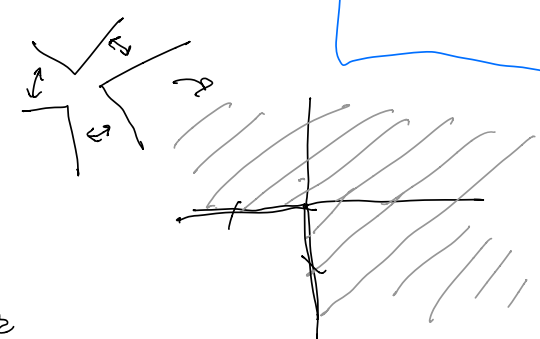
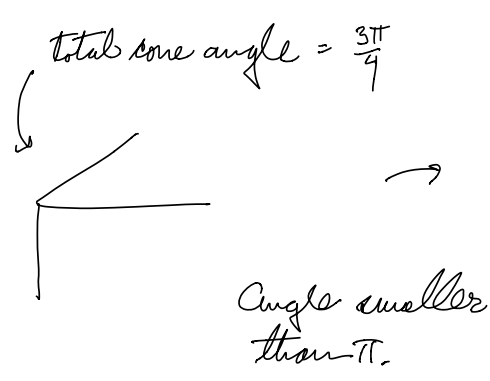
Note that choosing  $x$  and  $y$  for our coordinates upstairs corresponds to using polar coordinates  $r = e^x$   $\theta = e^{iy}$  downstairs

$$\exp(x+iy) = e^x \cdot e^{iy} = r \cdot \theta.$$

for polar coordinates  $z \mapsto z^n$  becomes  $(r, \theta) \mapsto (r^n, n\theta)$ .



$(r, \theta)$  coordinates  
 $0 \leq r \leq R_p$   
 $\theta_0 \leq \theta \leq \theta_1$

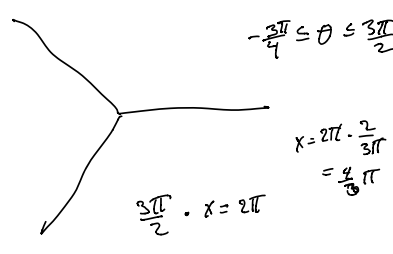


$(r, \theta) \mapsto (r^\alpha, \alpha\theta + \text{const.})$

$z \mapsto z^\alpha$

$\frac{3\pi}{2}, \alpha = 2\pi$   
 $\alpha = \frac{4}{3}$

$z \mapsto z^{4/3}$   
 $-\pi \leq \theta \leq \pi$   
 $-\frac{2\pi}{3} \leq \theta \leq \frac{3\pi}{2}$



Adding in sheets of this form give us transition functions of the form  $z \mapsto \lambda z^\beta + c$  where  $z^\beta$  is a branch of the power function.

3 points.

① There is a Riemann surface atlas  $\mathcal{A}$  for  $P$  (according to the strict definition of what a Riemann surface atlas is).

This definition creates a smooth surface (with a tangent bundle) which is homeomorphic to  $P$ .

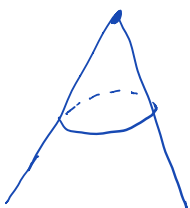
② Our intuition does not exactly agree with the strict definition. We would like some of the structure of  $P$  beyond just

the topology to be reflected in  $\mathcal{A}$ . In particular where  $P$  has a recognizable conformal structure we would like this to agree with the conformal structure given by  $\mathcal{A}$ .

③ Claim that any two atlases for  $P$  which are conformal away from the vertices are equivalent.

This says that even though  $P$  is not smooth itself  $P$  the conformal structure on  $P - \{\text{vertices}\}$  determines a unique conformal structure on all of  $P$ .

Simplest example: cone in  $\mathbb{R}^3$  with



cone angle  $\alpha$ .

say we have

Recall the theorem about isolated singularities.

3 cases:

Removable singularity

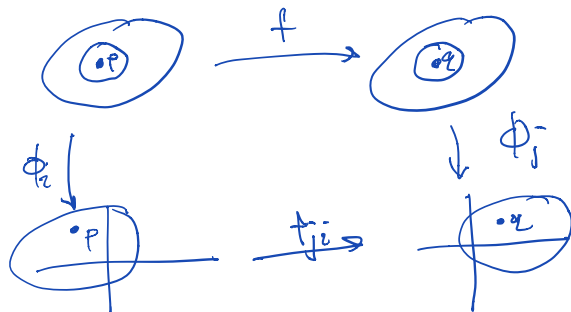
Pole

Essential singularity.

Theorem. (Removable singularities for atlases.)

Let  $R$  and  $R'$  be Riemann surfaces. Let  $\Sigma$  and  $\Sigma'$  be discrete subsets of  $R$  and  $R'$  and let  $f: R \rightarrow R'$  be a homeomorphism taking  $\Sigma$  to  $\Sigma'$  which is a holomorphic map from  $R - \Sigma$  to  $R' - \Sigma'$ . Then  $f$  is in fact a holomorphic map from  $R$  to  $R'$ .

Proof.





Need to check that  $f_{jz}$  is holomorphic.

$f_{jz}$  is a homeomorphism which is holomorphic away from an isolated singular point.

It follows from the classical removable singularities theorem that  $f$  is holomorphic at  $p$ .

