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## Diffusion Limits for MCMC Paths

#### Alexandros Beskos

Statistical Science, UCL

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Joint work with: Natesh Pillai, Gareth Roberts, Andrew Stuart

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Metropolis-F	lastings			

- **Objective:** Sample distribution  $\pi_n : \mathbb{R}^n \mapsto \mathbb{R}^+$ .
- **Method:** Construct Markov chain reversible w.r.t. *π*<sub>n</sub> and simulate up to stationarity.
- 1. Propose move  $X \rightarrow Y$  according to user-specified

$$q_n(X,dY)=q_n(X,Y)dY$$

2. Accept Y with probability

$$a_n(X,Y) = 1 \wedge \frac{\pi_n(Y)q_n(Y,X)}{\pi_n(X)q_n(X,Y)}$$

otherwise stay at X.

3. Simulate  $X^{(1)}, X^{(2)}, \dots$  up to equilibrium.

### Local MCMC Algorithms

Proposed move could be:

$$Y = X + \sqrt{h_n} Z, \quad Z \sim N(0, I_n)$$

giving Random-Walk Metropolis (RWM) algorithm.

It could also be:

$$Y = X + \frac{h_n}{2} \nabla \log \pi_n(X) + \sqrt{h_n} Z$$

giving Metropolis-adjusted Langevin algorithm (MALA).

 Goldilocks Principle: Step-size h<sub>n</sub> should neither be "too small" or "too big".

#### **Goldilocks** Principle



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### Some Questions

- What is the "optimal" choice of *h<sub>n</sub>*, *a<sub>n</sub>*?
- What is the limiting behaviour of MCMC as  $n \to \infty$ ?
- Adaptive schemes have tried to address *h<sub>n</sub>* selection dynamically (e.g. Haario, Atchad, Roberts, Rosenthal, Andrieu, Moulines).
- Here we look at non-dynamic setting.

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• Consider iid target distribution

$$\pi_n(X) = \prod_{i=1}^n f(x_i)$$

and apply RWM, MALA for  $h_n = I \times \Delta t$ .

• Scale step-size as:

$$RWM: \Delta t = n^{-1}, MALA: \Delta t = n^{-1/3}$$

and bring MCMC points close:





Theorem (Roberts et al., 97; Roberts & Rosenthal, 98)
Continuous time process x<sup>([t/\Delta t])</sup> converges weakly to:

$$\frac{dx}{dt} = \frac{1}{2} s(l) \left(\log f\right)'(x) + \sqrt{s(l)} \frac{dW}{dt}$$

for speed function:

$$s(l)=l^2a(l)$$

where a(I) is limiting acceptance probability:

$$a(I) = \lim_{n} E\left[a_n(x, y)\right] \in (0, 1)$$

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- MCMC similar (for large *n*) to **Euler scheme** on diffusion.
- Speed function *s*(*I*) is maximised for

*RWM* : a(l) = 0.234*MALA* : a(l) = 0.574

• 'Mixing' cost of algorithms is  $\mathcal{O}(\Delta t^{-1})$ , so:

RWM : n MALA : n<sup>1/3</sup>

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 Efficiency can be compared in terms of integrated autocorrelation time:

$$au_{g}(h_{n}) = 1 + \sum_{j=1}^{\infty} Corr(g(x^{(0)}), g(x^{(j)}))$$

so that:

$$Var(rac{\sum_{j=1}^J g(x^{(j)})}{J}) pprox rac{Var[g(x)]}{J} imes au_g$$

Because of diffusion limit we can factorise:

$$(\tau_g(h_n))^{-1} \approx s(I) c_g \times \Delta t$$

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• We considered targets:

$$rac{d\pi}{d\pi_0}(X) \propto \exp(-\Phi_n(X))$$

where

$$\pi_0 = \prod_{i=1}^n \frac{1}{\lambda_i} f(\frac{x_i}{\lambda_i}); \ \lambda_i = i^{-\kappa}$$

- RWM:  $h_n = I \times n^{-2\kappa-1}$ , MALA:  $h_n = I \times n^{-2\kappa-1/3}$
- We use mean square jump:

$$M(n) = E |x^{(j+1)} - x^{(j)}|^2$$

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- Consider the norm  $||X||_s = \left(\sum_{i=1}^n i^{2s} x_i^2\right)$
- Assume that  $\Phi_n$  is such that:

$$egin{aligned} \Phi_n(X) &\geq M \ &|\Phi_n(Y) - \Phi_n(X)| \leq L(\|X\|_s, \|Y\|_s) \|X - Y\|_{s'} \ &|\Phi_n(X)| \leq C(1 + \|X\|_{s''}) \end{aligned}$$

for *L* continuous, and  $s, s', s'' < \kappa - 1/2$ .

• Then, we can factorise out s(I):

MALA: 
$$M(n) = s(l) \times n^{-2\kappa - 1/3}$$
  
RWM:  $M(n) = s(l) \times n^{-2\kappa - 1}$ 

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• Target is on Hilbert space:

$$\frac{d\pi}{d\pi_0}(X) = \exp\{-\Phi(X)\}$$

with  $\pi_0 \sim N(0, C)$ .

• 
$$C e_i = \lambda_i^2 e_i, \quad \lambda_i = i^{-\kappa}$$

MCMC trajectory on discretised space converges to SPDE:

$$\frac{dX}{dt} = \frac{1}{2} s(l) \left( -X - C \nabla \Phi(X) \right) + \sqrt{s(l) C} \frac{dW}{dt}$$

• Pillai & Stuart, 09.

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# **Conditioned Diffusions**

• Sample X = X(u):

$$rac{dX}{du} = g(X) + \gamma rac{dW}{du}$$

#### Conditioned on:

- Diffusion bridge: X(0) and X(1) (Molecular Dynamics)
- Interpolate data:  $X(i\Delta)_{i=0}^{N}$  (Econometrics)
- Noisy observation of *X*(*u*) (Signal Filtering)



- Navier-Stokes inverse problem for fluid dynamics.
- Sample  $X_0 \in L^2(\Omega, \mathbb{R}^2)$  initial condition for PDE:

$$\frac{\partial X}{\partial t} + X \cdot \nabla X = \nu \Delta X + g, \quad X(0) = X_0.$$

• Conditioned on (Lagrangian) observations:

$$\begin{aligned} \frac{dz_j}{dt} &= X(z_j, t), \quad z_j(0) = z_{j,0} , \\ y_{j,k} &= z_j(t_k) + N(0, \Sigma_{j,k}) . \end{aligned}$$

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• (Assuming Gaussian prior on X<sub>0</sub>.)

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• We studied complexity of Local MCMC algorithms in high (sometimes infinite!) dimensions.

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- Obtained interpretation of RWM and MALA as Euler approximations of a diffusion.
- Diffusion limit allows for uniform optimization.
- Results can be extended to non-trivial targets.
- Non-product targets can give SPDE limits.

# Some Further Directions

- Proving SPDE led to development of new framework for proving convergence.
- New framework avoids enormous complexities with using generators.
- In the case of RWM and MALA it avoids many of the conditions required in previous works.
- We are currently applying new framework to Hybrid Monte-Carlo algorithm, with evidence of hypoelliptic diffusion limit.

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