Likelihood inference and computational problems for a random set model

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March 20, 2009

Heather dataset (Diggle, 1981)



Heather plants in a 10×20 m window W (Jädraås, Sweden).

Grow from seedlings into (roughly) hemispherical bushes \Rightarrow \cup heather plants "seen from above" = union of discs, U_X , where X is a disc process.

Observe only $\mathcal{U}_X \cap W$.

$\mathcal{U}_X = \text{germ-grain model}$:

General germ-grain model:

$$\mathcal{U}_X = \bigcup_i \left(u_i + K_i \right)$$

where

• the germs $\{u_i\} \subset \mathbb{R}^d$ form a (locally finite) point process,

• the primary grains $K_i \subset \mathbb{R}^d$ are random compact sets.

Heather dataset: $K_i = b(0, r_i)$ and

$$\mathcal{U}_X = \bigcup_i b(u_i, r_i).$$

Remarks

• *Theorem*: Any random closed set

(i.e., a locally finite union of compact convex random sets) \sim germ-grain model with convex and compact grains.

However,

- in practice, need a much smaller class of models;
- often a Poisson disc process (Boolean model).

Poisson disc process

- $\{u_i\}$ ~ Poisson point process
- $\{r_i\}$ IID and independent of $\{u_i\}$
- Advantages: well-studied (moment results).
- Disadvantages/complications:
 - lack of interaction;
 - grains unobservable \Rightarrow density/likelihood for \mathcal{U}_X ???
 - ► MCMC missing data approach, simulating X | U_X ∩ W: not an option: grains only ≈ discs & digital image ⇒ difficult to indentify circular structures.

Fitting a Poisson disc model (Diggle, 1981)



- Stationary; mark distribution = truncated Weibull.
- Fitted by a minimum contrast method *.
- Simulations: visual impression not good.
- "A model incorporating interaction may be appropriate".

* Further (non-likelihood-based) approaches: Dupač (1980), Serra (1980), Hall (1985, 1988), Ripley (1988), Cressie (1993), Stoyan *et al.* (1995), Molchanov (1997), ... Our (non-Poisson) model (Møller & Helisova, 2008a,b)

- Pragmatic approach:
- a) Specify and fit a Poisson disc process.
- b) Extend it to a certain interacting disc process model...
- ... which makes it possible to handle
- (1) edge effects;
- (2) individual grains are unobservable;

• ... and which provides (the first work on) simulation-based likelihood inference for a germ-grain model.

Some notation

Identify a finite collection of discs with a marked point pattern

$$x = \{(u_1, r_1), \ldots, (u_n, r_n)\} \subset S \times [0, \infty)$$

where $S \supset W$ is the (unknown!) bounded region for heather plant centers.



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The density

with respect to reference/fitted Poisson disc process,

$$f_{\theta}(x) = \frac{1}{c_{\theta}} \exp\left(\theta_1 A(\mathcal{U}_x) + \theta_2 L(\mathcal{U}_x) + \theta_3 N_{\rm cc}(\mathcal{U}_x) + \theta_4 N_{\rm h}(\mathcal{U}_x) + \ldots\right)$$

where

$$A =$$
area, $L =$ perimeter,

 $N_{
m cc}=\#$ connected components, $N_{
m h}=\#$ holes.



A connected component Markov process (Baddeley & Møller, 1989)

$$f_{\theta}(x) = \frac{1}{c_{\theta}} \prod_{y \subseteq x \text{ con. comp.}} \phi_{\theta}(y)$$

where

 $\phi_{\theta}(y) = \exp\left(\theta_1 A(\mathcal{U}_y) + \theta_2 L(\mathcal{U}_y) + \theta_3 + \theta_4 N_{\rm h}(\mathcal{U}_y)\right)$



Special cases

• Area-interaction process (with varying radii) if $\theta_2 = \theta_3 = \theta_4 = 0$ and $\theta = \theta_1$: $f_{\theta}(x) = \frac{1}{c_{\theta}} \exp(\theta A(U_x))$

(Widom & Rowlinson, 1970; Baddeley & Van Lieshout, 1995).

- Quermass-interaction process if $\theta_3 + \theta_4 = 0$ and $\theta = (\theta_1, \theta_2, \theta_3)$: $f_{\theta}(x) = \frac{1}{c_{\theta}} \exp(\theta_1 A(\mathcal{U}_x) + \theta_2 L(\mathcal{U}_x) + \theta_3 \chi(\mathcal{U}_x))), \quad \chi = N_{cc} - N_h$ (Kendall, Van Lieshout & Baddeley, 1999).
- Continuum random-cluster model (with varying radii) if $\theta_1 = \theta_2 = \theta_4 = 0$ and $\theta = \theta_3$: $f_{\theta}(x) = \frac{1}{c_{\theta}} \exp(\theta N_{cc}(U_x))$

(Klein, 1982).



1) Reference Poisson disc process: $S = [0, 30] \times [0, 30]$, intensity = 0.2, IID radii ~ Uniform[0, 2]. 2) $(\theta_1, \theta_2, \theta_3, \theta_4) = (0.1, 0, 0, 0).$ 3) $(\theta_1, \theta_2, \theta_3, \theta_4) = (-0.1, 0, 0, 0).$ 4) $(\theta_1, \theta_2, \theta_3, \theta_4) = (0.6, -1, 1, 0).$ 5) $(\theta_1, \theta_2, \theta_3, \theta_4) = (0.6, -1, 2, 0).$ 6) $(\theta_1, \theta_2, \theta_3, \theta_4) = (0.6, -1, 5, 0).$

Parameter space

Under mild conditions

$$f_{\theta}(x) = \frac{1}{c_{\theta}} \exp\left(\theta_1 A(\mathcal{U}_x) + \theta_2 L(\mathcal{U}_x) + \theta_3 N_{cc}(\mathcal{U}_x) + \theta_4 N_{h}(\mathcal{U}_x)\right)$$

is a regular exponential family model with parameter space

 $\Theta = \mathbb{R}^4$ if the radii are bounded,

or in general

$$\Theta = \{ (\theta_1, \theta_2, \theta_3, \theta_4) \in \mathbb{R}^4 : \int \exp\left(\pi \theta_1 r^2 + 2\pi \theta_2 r\right) Q(\mathrm{d}r) < \infty \}$$

where Q is the mark distribution under the reference Poisson disc process.

A fundamental characteristic

(Papangelou) conditional intensity:

$$\lambda_{\theta}(x,(u,r)) = f_{\theta}(x \cup \{(u,r)\})/f_{\theta}(x)$$

for $x = \{(u_1, r_1), \dots, (u_n, r_n)\} \subset S \times [0, \infty)$, $(u, r) \in S \times [0, \infty)$.

$$\lambda_{\theta}(x, (u, r)) = \text{``local characteristic'';} \\ -\log \lambda_{\theta}(x, (u, r)) = \text{``local energy''.}$$

Important because

- $\lambda_{\theta} \leftrightarrow f_{\theta}$ but λ_{θ} does not involve c_{θ} ;
- specifies local Markov properties;
- appears in the Hastings ratio of Metropolis-Hastings birth-death algorithm (Geyer & Møller, 1994; Green, 1995).

In many cases, local stability and hence geometric ergodicity.

Key tool (for many things incl. λ_{θ}): Power tessellation







Book keeping in Metropolis-Hastings birth-death algorithm

(www.math.aau.dk/~jm/Codes.union.of.discs) Keep track on (A, L, N_{cc}, N_{h}) by also keeping track on $N_{c} = \#$ cells, $N_{ie} = \#$ interior edges, $N_{iv} = \#$ interior vertices, and using

$$egin{aligned} A &= \sum ext{areas of cells} \ L &= \sum ext{lengths of arcs} \ N_{ ext{h}} &= N_{ ext{cc}} - N_{ ext{c}} + N_{ ext{ie}} - N_{ ext{iv}} \end{aligned}$$



Local Markov property $\lambda_{q}(x, (u, r)) =$

$$\exp\left[\theta_1\left(A(\mathcal{U}_{x\cup\{(u,r)\}})-A(\mathcal{U}_x)\right)+\theta_2\left(L(\mathcal{U}_{x\cup\{(u,r)\}})-L(\mathcal{U}_x)\right)+\right.\\\left.\left.\theta_3\left(N_{cc}(\mathcal{U}_{x\cup\{(u,r)\}})-N_{cc}(\mathcal{U}_x)\right)+\theta_4\left(N_{h}(\mathcal{U}_{x\cup\{(u,r)\}})-N_{h}(\mathcal{U}_x)\right)\right]\right]$$

depends on x only through those U_x -cc which intersect b(u, r).



If $\theta_3 = \theta_4$: depends only on those $b(u_i, r_i)$ which intersect b(u, r).

Handle edge effects by exploting a spatial Markov property Split X into

 $X^{(a)}$ (full circles), $X^{(b)}$ (dashed circles), $X^{(c)}$ (dotted circles)



Spatial Markov property



- $X^{(a)}$ and $X^{(c)}$ are conditionally independent given $X^{(b)} = x^{(b)}$;
- $X^{(a)}|_{X^{(b)}} \sim X^{(a)}|_{V}$, where $V := W \cap \mathcal{U}_{x^{(b)}}$;
- for feasible $x^{(a)}$ (i.e. $\mathcal{U}_{x^{(a)}} \subseteq W$ and $\mathcal{U}_{x^{(a)}} \cap V = \emptyset$), $f_{\theta}(x^{(a)}|V) = \frac{1}{c_{\theta}(V)} \exp\left(\theta_1 A(\mathcal{U}_{x^{(a)}}) + \theta_2 L(\mathcal{U}_{x^{(a)}}) + \theta_3 N_{cc}(\mathcal{U}_{x^{(a)}}) + \theta_4 N_{h}(\mathcal{U}_{x^{(a)}})\right)$.

Heather data: conditional log likelihood



$$\begin{split} L_{c}(\theta) &= \log f_{\theta}(x^{(a)}|V) \\ &= \theta_{1}A(\mathcal{U}_{x^{(a)}}) + \theta_{2}L(\mathcal{U}_{x^{(a)}}) + \theta_{3}N_{cc}(\mathcal{U}_{x^{(a)}}) + \theta_{4}N_{h}(\mathcal{U}_{x^{(a)}}) - \log c_{\theta}(V) \end{split}$$

with $c_{\theta}(V)$ approximated by MCMC methods.

Unconditional log likelihood

Pretend S = W. Let $Y = \bigcup_i b(u_i, r_i) \cap W$.



Approximate the log (unconditional) likelihood by *ignoring edge effects*,

$$L_{u}(\theta) = \theta_{1}A(Y) + \theta_{2}L(Y) + \theta_{3}N_{cc}(Y) + \theta_{4}N_{h}(Y) - \log c_{\theta}$$

with c_{θ} approximated by MCMC methods.

Some remarks

- Rather different "conditional" and "unconditional" MLE's.
- Preferable(?) to use L_c(θ) (accounts for edge effects); the effect of using L_u(θ) is less well-understood.
- Loss of information in using $L_c(\theta)$:

$$A(Y) = 100.28, \quad L(Y) = 382.82, \quad N_{\rm cc}(Y) = 56, \quad N_{\rm h}(Y) = 6,$$

are about twice as large as

 $A(\mathcal{U}_{X^{(a)}}) = 45.6, \quad L(\mathcal{U}_{X^{(a)}}) = 190, \quad N_{\rm cc}(\mathcal{U}_{X^{(a)}}) = 32, \quad N_{\rm h}(\mathcal{U}_{X^{(a)}}) = 2.$

- Specification of reference Poisson disc process is important. (We compared results using 3 different reference processes.)
- ▶ But the same overall conclusion (Wald tests; summaries):

$$\theta_1 < 0, \quad \theta_2 > 0, \quad \theta_3 < 0, \quad \theta_4 = 0,$$

SO

$$f_{\theta}(x) = \frac{1}{c_{\theta}} \exp\left(\theta_1 A(\mathcal{U}_x) + \theta_2 L(\mathcal{U}_x) + \theta_3 N_{cc}(\mathcal{U}_x)\right).$$

• The quermass-interaction process, i.e. $\theta_3 + \theta_4 = 0$ and

$$f_{ heta}(x) = rac{1}{c_{ heta}} \exp\left(heta_1 A(\mathcal{U}_x) + heta_2 L(\mathcal{U}_x) + heta_3 \chi(\mathcal{U}_x)
ight), \quad \chi = N_{
m cc} - N_{
m h}$$

was rejected.

Some simulations of 3 reference Poisson disc processes

First two: fitted by a method from Hall (1985) (using a truncated normal and uniform mark dist.). Third: (partly) taken from Laslett *et al.* (1985)



Misfit in all 3 cases: too many small components.

Third case: too low area fraction.

Some simulations of 3 fitted (A, L, N_{cc}) -interaction models



Model control based on various contact distribution functions and covariance function: no misfit for the two first models.

Shape characteristics: some misfit, possibly since the heather data are rather smooth while a disc process is naturally more rugged.

References

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Software: www.math.aau.dk/~jm/Codes.union.of.discs